



Marine Accident Analysis of Collisions and Groundings:

How to learn from past incidents to avoid them in the future

Webinar: International Union of Marine Insurance

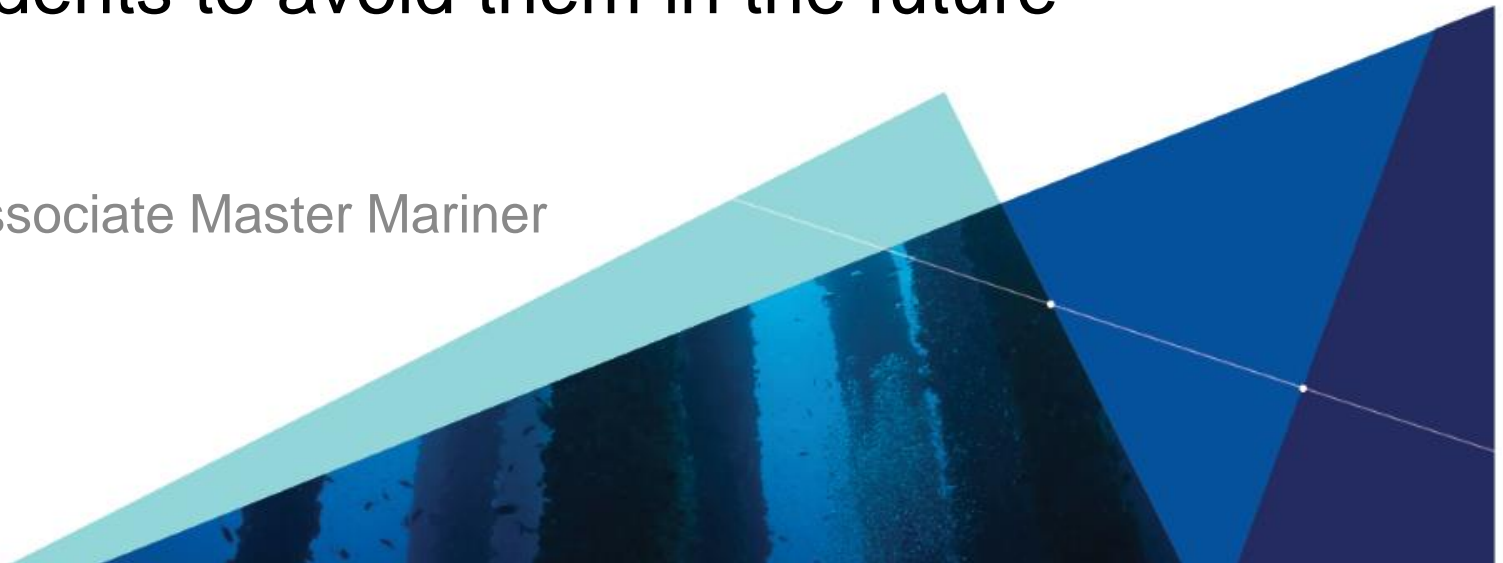
10 April 2018





Marine Accident Analysis of Collisions and Groundings: How to learn from past incidents to avoid them in the future

By Captain Paul Whyte MBE AFNI, Associate Master Mariner





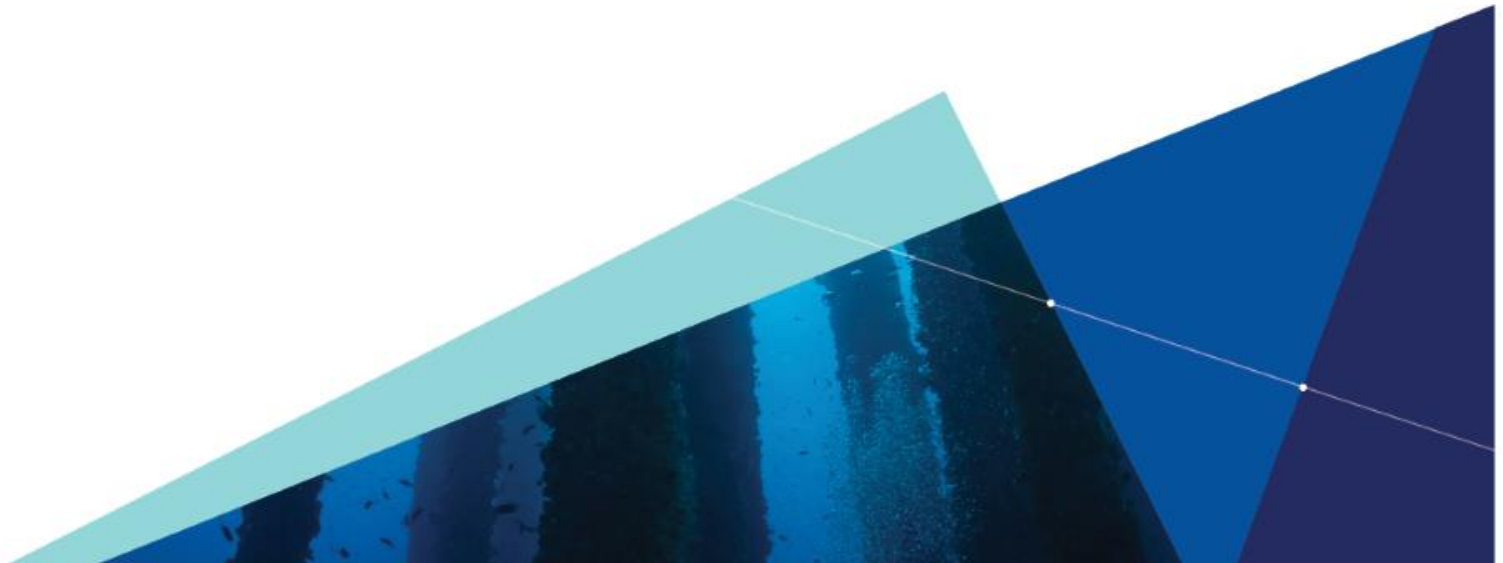
Discussion Topics

- Situational Awareness
- Surveying the 3-D waterspace
- International Regulations for Preventing Collisions at Sea, 1972
- How Electronic Evidence Works
- Casualty Investigation and Accident Analysis
- Case Studies
- Conclusions.





Situational Awareness





Situational Awareness: The Mystery

“Navigation is not so much knowing where you are, but knowing where you should not be”

“Collisions are usually avoided by awareness, anticipation, application and action”



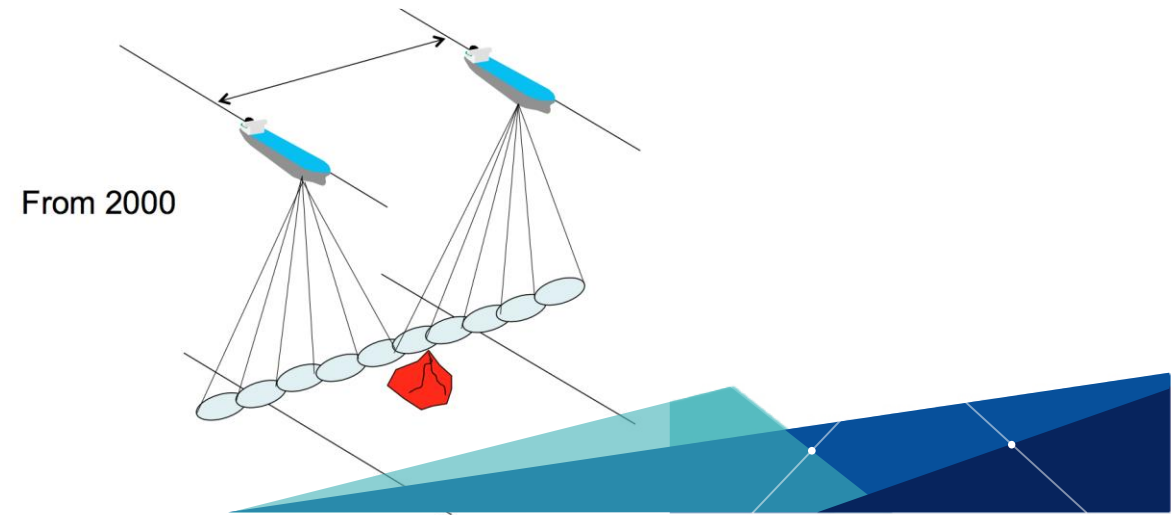
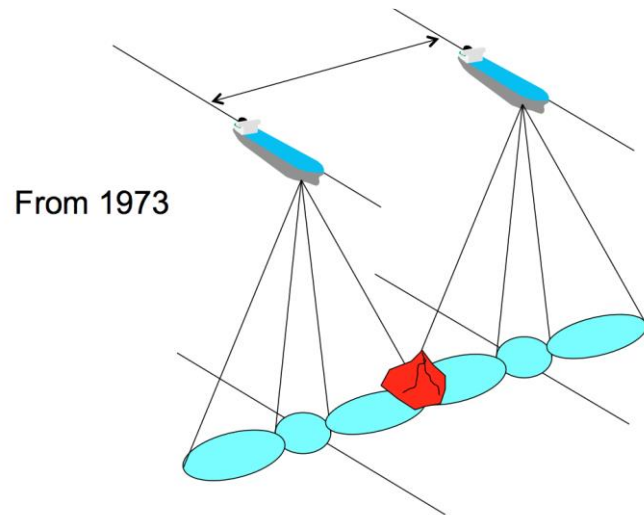
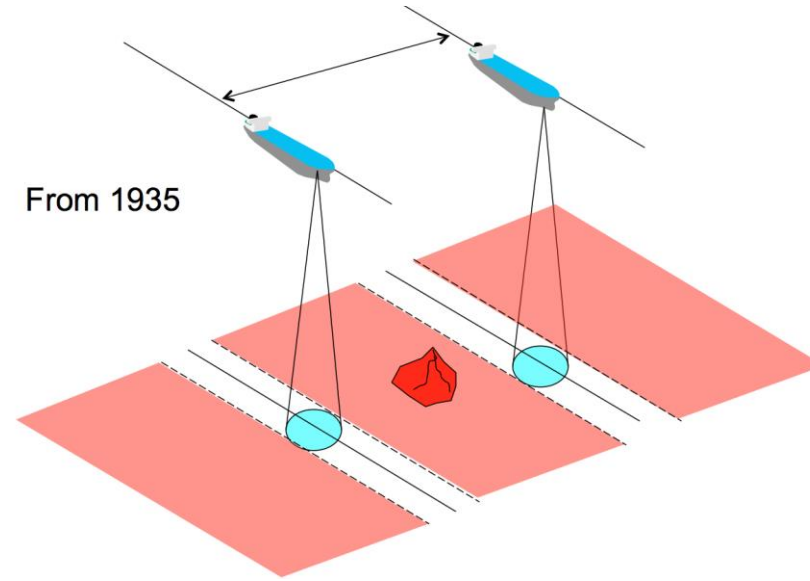
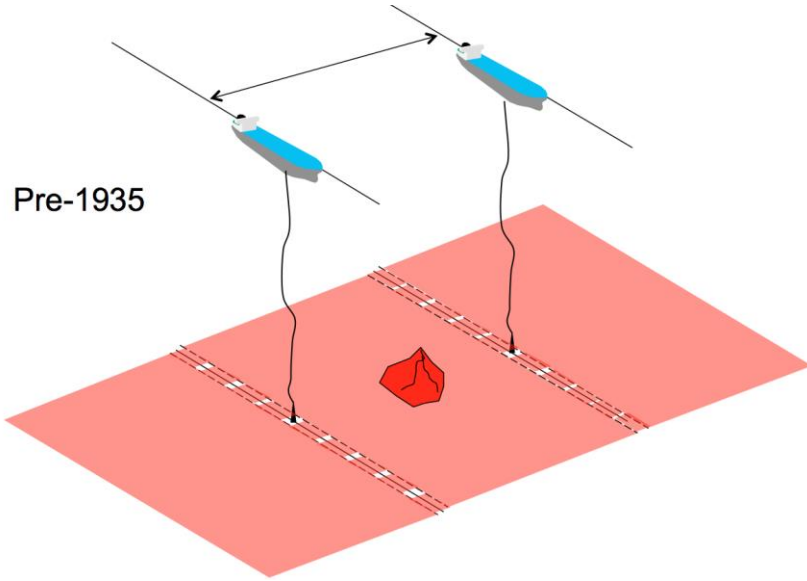


Surveying the 3-D waterspace

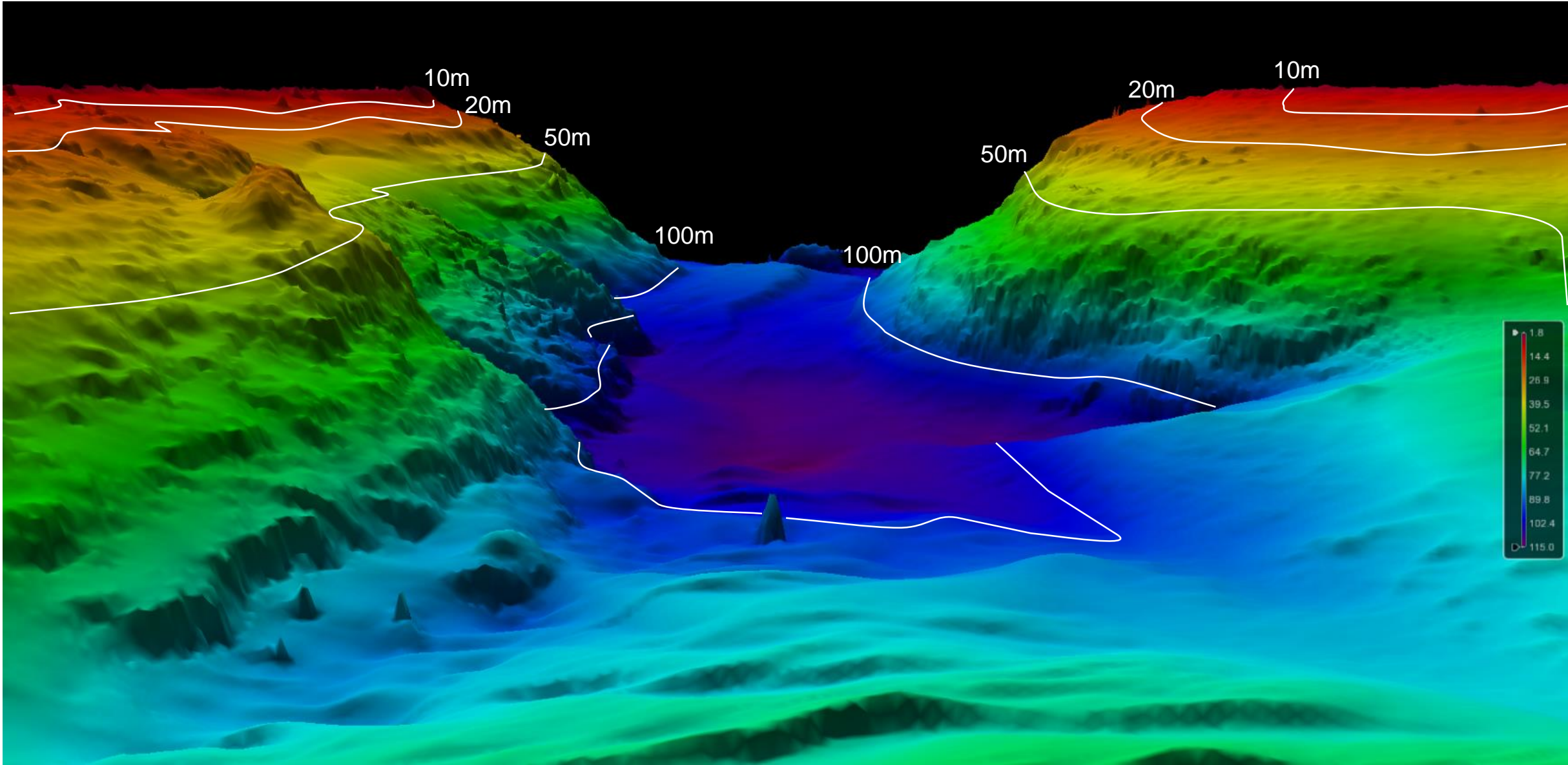




The Basics of Surveying

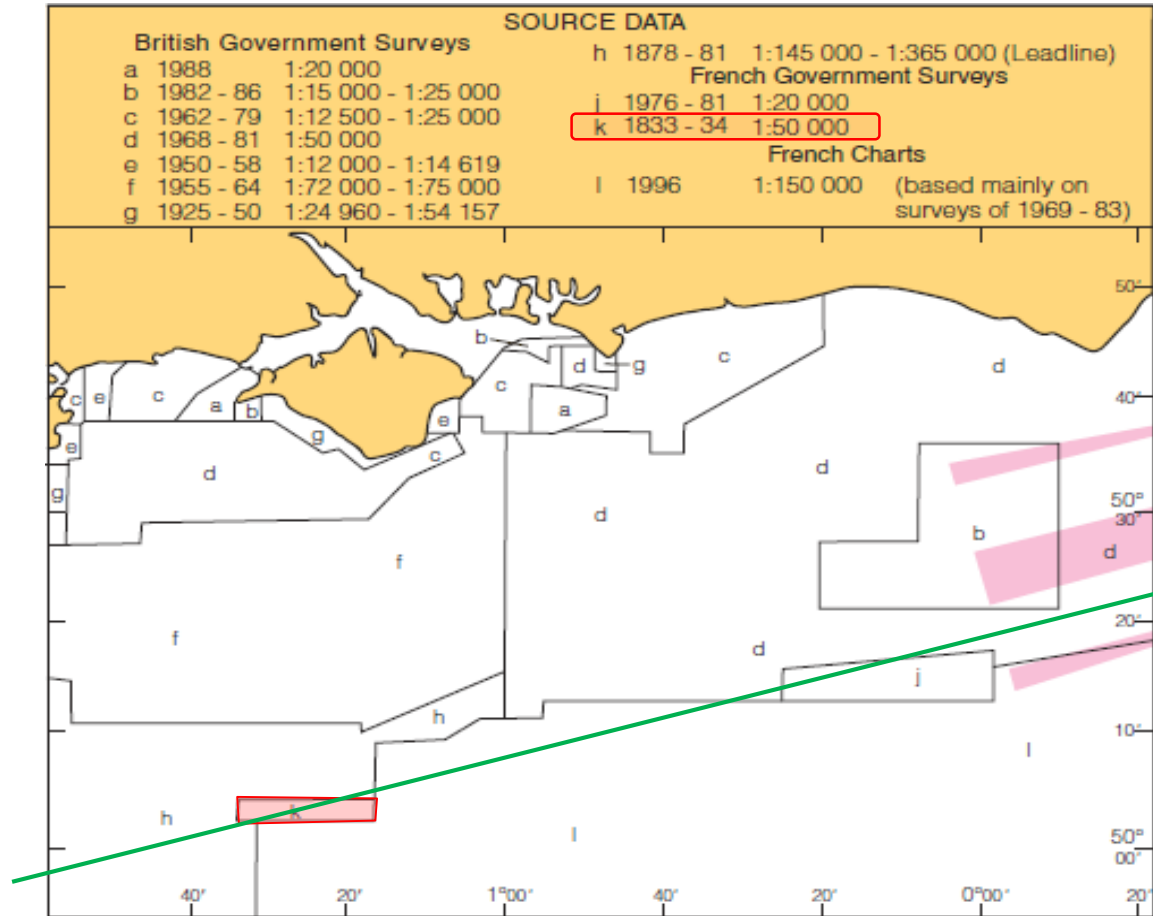


LOC The Basics of Surveying





Paper Charts: Source Data Diagram



- English Channel Chart
- Area K, NE lane Dover Straits TSS
- Today we consider quality instead of the age of the survey





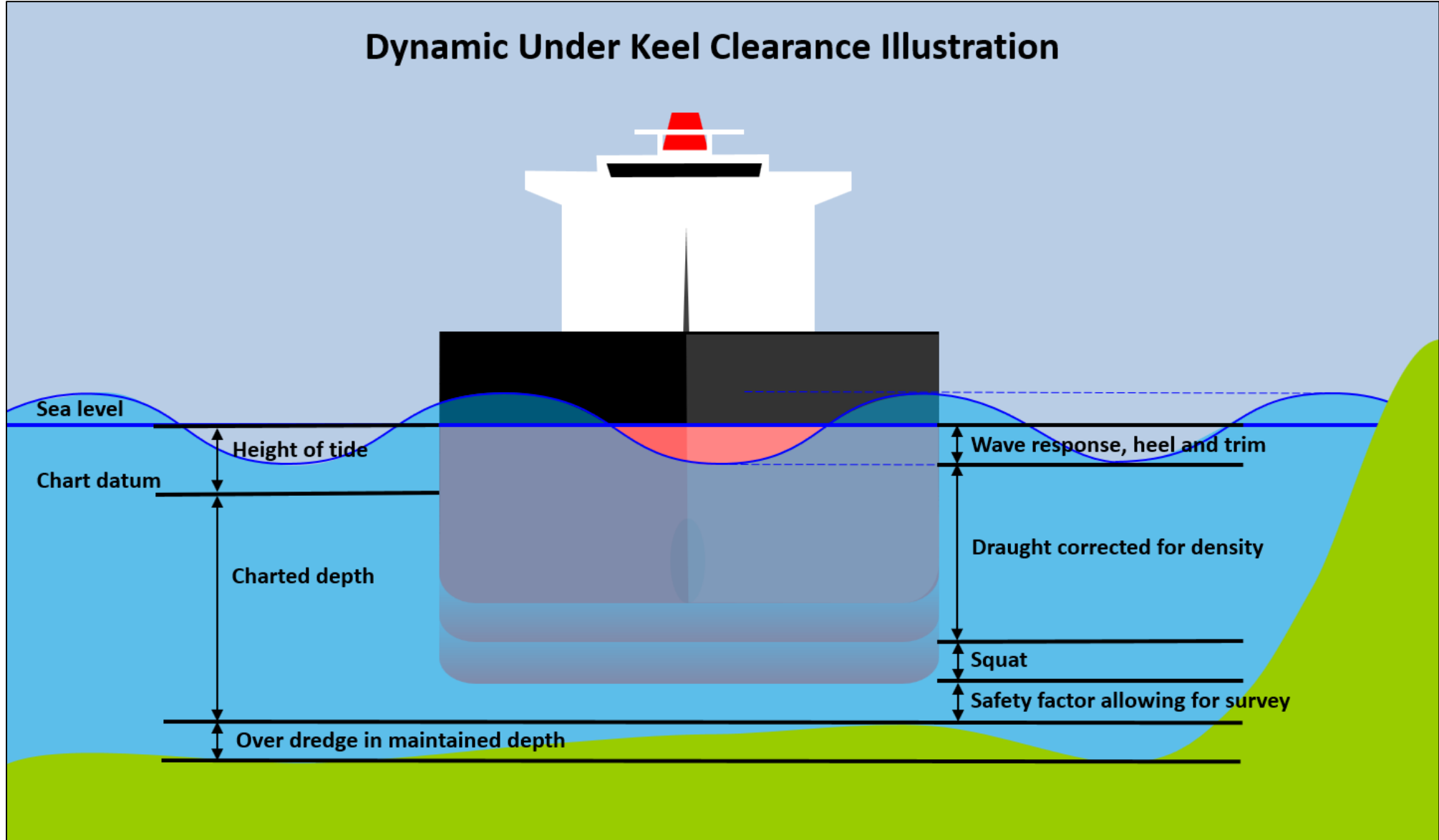
Electronic Charts: Category of Zones of Confidence

| 1 | 2 | 3 | 4 | 5 | | | | | | |
|------------------|--|---|---|---|-----------|--------------|----|-------|----|-------|
| ZOC ¹ | Position Accuracy ² | Depth Accuracy ³ | Seafloor Coverage | Typical Survey Characteristics ⁵ | | | | | | |
| A1 | ±5m + 5% depth | 0.5m + 1% depth | Full area search undertaken. Significant seafloor features detected ⁴ and depths measured. | Controlled, systematic survey ⁶ . High position and depth accuracy achieved using DGPS or a minimum of three high quality lines of position (LOP) and a multibeam, channel or mechanical sweep system. | | | | | | |
| | | <table border="1"> <tr> <th>Depth (m)</th> <th>Accuracy (m)</th> </tr> <tr> <td>10</td> <td>± 0.6</td> </tr> <tr> <td>30</td> <td>± 0.8</td> </tr> <tr> <td>100</td> <td>± 1.5</td> </tr> <tr> <td>1000</td> <td>± 10.5</td> </tr> </table> | | | Depth (m) | Accuracy (m) | 10 | ± 0.6 | 30 | ± 0.8 |
| Depth (m) | Accuracy (m) | | | | | | | | | |
| 10 | ± 0.6 | | | | | | | | | |
| 30 | ± 0.8 | | | | | | | | | |
| 100 | ± 1.5 | | | | | | | | | |
| 1000 | ± 10.5 | | | | | | | | | |
| A2 | ± 20m | 1.0m + 2% depth | Full area search undertaken. Significant seafloor features detected ⁴ and depths measured. | Controlled, systematic survey ⁶ achieving position and depth accuracy less than ZOC A1 and using a modern survey echo sounder ⁷ and a sonar or mechanical sweep system. | | | | | | |
| | | <table border="1"> <tr> <th>Depth (m)</th> <th>Accuracy (m)</th> </tr> <tr> <td>10</td> <td>± 1.2</td> </tr> <tr> <td>30</td> <td>± 1.6</td> </tr> <tr> <td>100</td> <td>± 3.0</td> </tr> <tr> <td>1000</td> <td>± 21.0</td> </tr> </table> | | | Depth (m) | Accuracy (m) | 10 | ± 1.2 | 30 | ± 1.6 |
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| 30 | ± 1.6 | | | | | | | | | |
| 100 | ± 3.0 | | | | | | | | | |
| 1000 | ± 21.0 | | | | | | | | | |
| B | ± 50m | 1.0m + 2% depth | Full area search not achieved; uncharted features, hazardous to surface navigation are not expected, but may exist. | Controlled, systematic survey achieving similar depth but lesser position accuracies than ZOC A2 using a modern survey echo sounder but no sonar or mechanical sweep system. | | | | | | |
| | | <table border="1"> <tr> <th>Depth (m)</th> <th>Accuracy (m)</th> </tr> <tr> <td>10</td> <td>± 1.2</td> </tr> <tr> <td>30</td> <td>± 1.6</td> </tr> <tr> <td>100</td> <td>± 3.0</td> </tr> <tr> <td>1000</td> <td>± 21.0</td> </tr> </table> | | | Depth (m) | Accuracy (m) | 10 | ± 1.2 | 30 | ± 1.6 |
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| 30 | ± 1.6 | | | | | | | | | |
| 100 | ± 3.0 | | | | | | | | | |
| 1000 | ± 21.0 | | | | | | | | | |
| C | ± 500m | = 2.0m + 5% depth | Full area search not achieved; depth anomalies may be expected. | Low accuracy survey or data collected on an opportunity basis such as soundings on passage. | | | | | | |
| | | <table border="1"> <tr> <th>Depth (m)</th> <th>Accuracy (m)</th> </tr> <tr> <td>10</td> <td>± 2.5</td> </tr> <tr> <td>30</td> <td>± 3.5</td> </tr> <tr> <td>100</td> <td>± 7.0</td> </tr> <tr> <td>1000</td> <td>± 52.0</td> </tr> </table> | | | Depth (m) | Accuracy (m) | 10 | ± 2.5 | 30 | ± 3.5 |
| Depth (m) | Accuracy (m) | | | | | | | | | |
| 10 | ± 2.5 | | | | | | | | | |
| 30 | ± 3.5 | | | | | | | | | |
| 100 | ± 7.0 | | | | | | | | | |
| 1000 | ± 52.0 | | | | | | | | | |
| D | Worse than ZOC C | Worse than ZOC C | Full area search not achieved, large depth anomalies may be expected. | Poor quality data or data that cannot be quality assessed due to lack of information. | | | | | | |
| U | Unassessed – the quality of the bathymetric data has yet to be assessed. | | | | | | | | | |

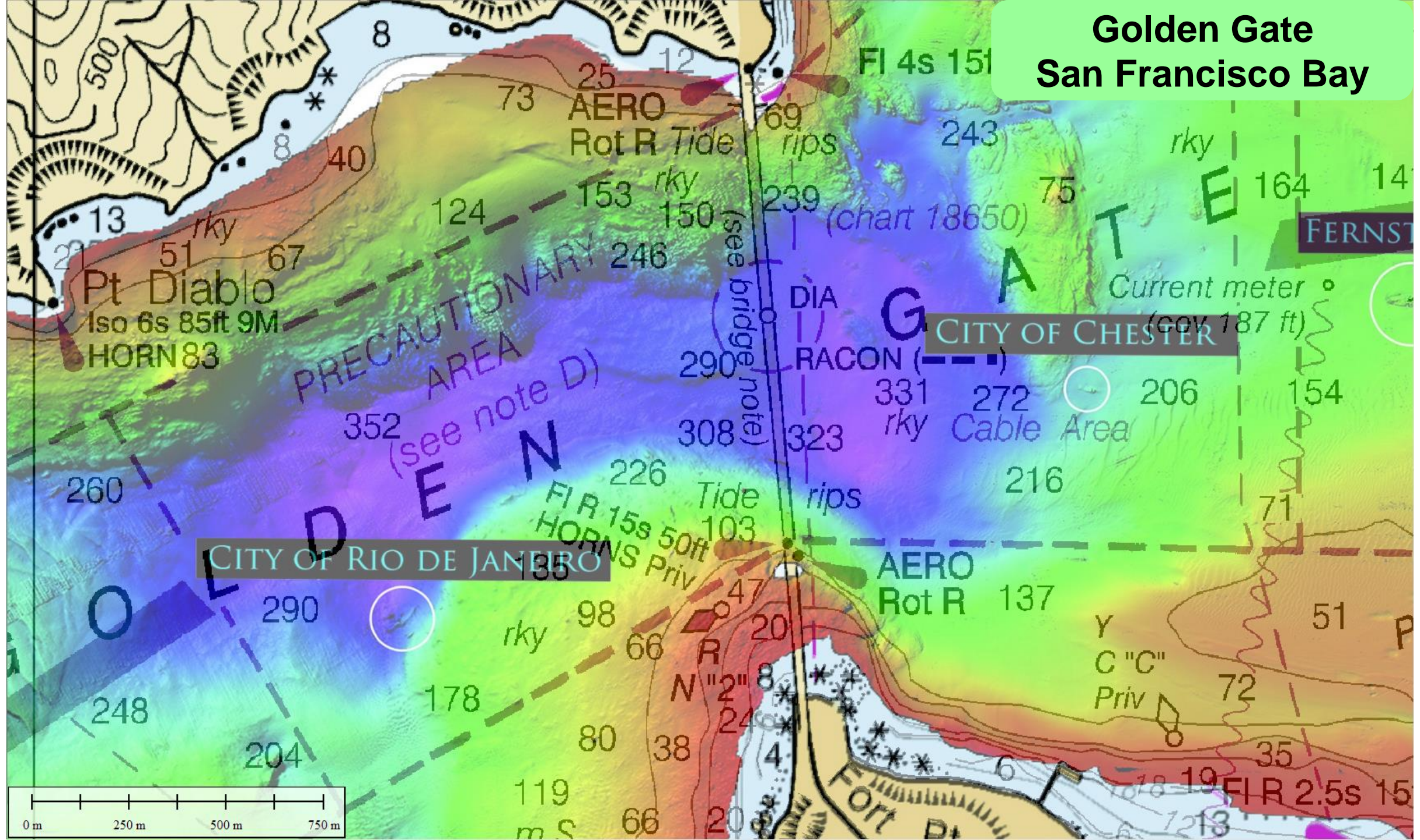
| ZOC 1 | CATZOC Symbol |
|-------|---------------|
| A1 | |
| A2 | |
| B | |
| C | |
| D | |
| U | |



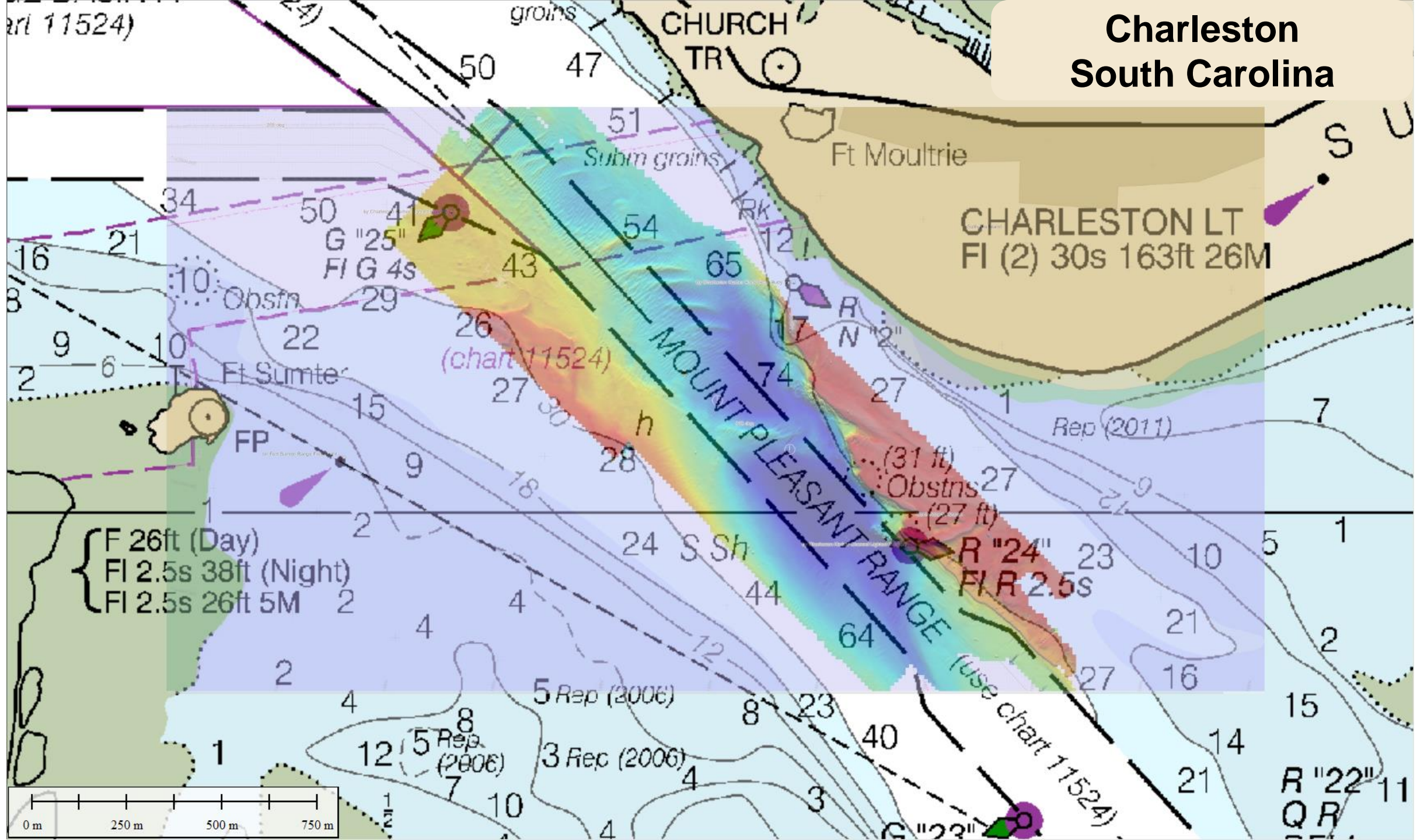
2-D Under Keel Clearance



Golden Gate San Francisco Bay

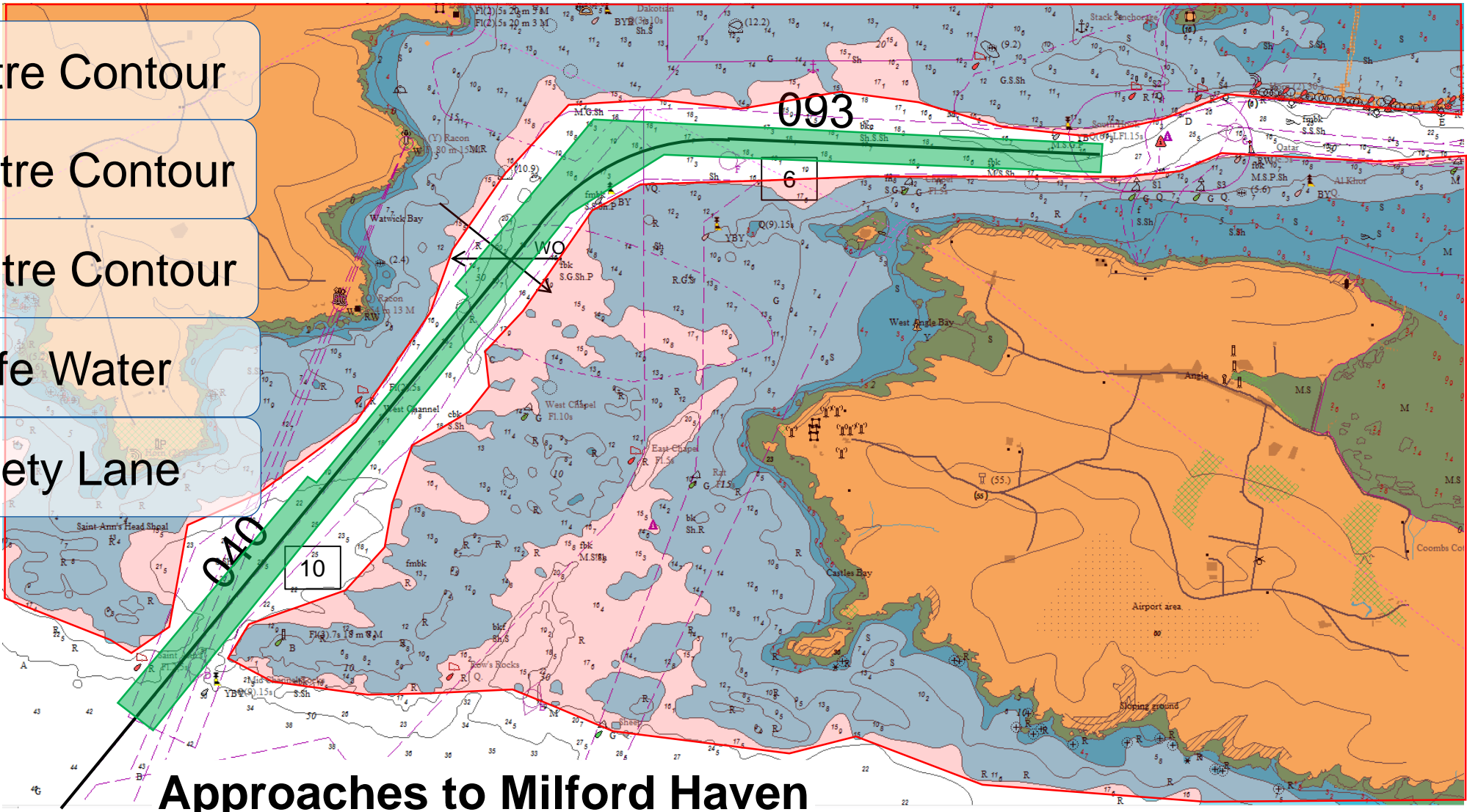


Charleston South Carolina



LOC Basics of Anti-Grounding

- 5-Metre Contour
- 10-Metre Contour
- 15-Metre Contour
- Safe Water
- Safety Lane



Approaches to Milford Haven



International Regulations to Prevent Collisions at Sea, 1972 (COLREGS)





Basics of the COLREGS

COLREGS:

- Introduced 1846
- 41 Rules plus 4 Annexes
- 8,600 Words
- Theory (no Practical) Test
- Revalidate every 5 years

UK HIGHWAY CODE:

- Introduced 1931
- 307 Rules plus 9 Annexes
- 25,000 words
- Theory and Practical Test
- Valid until 70 and re-test





Basics of the COLREGS

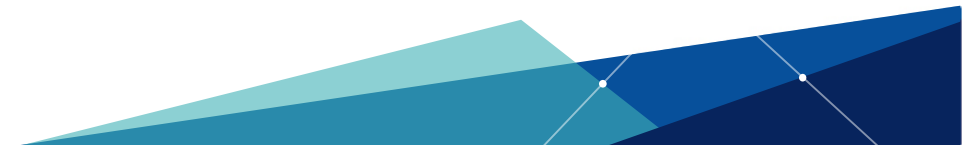
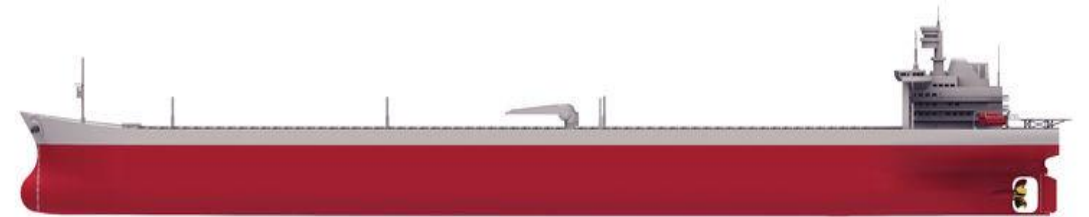
- **Awareness:** maintain a proper lookout (R5)
- **Anticipation:** safe speed (R6) gives space and time to assess
- **Application:** know COLREGS and particularly risk of collision (R7)
- **Action:** take positive and early action to avoid a collision (R8).





When does a risk of collision exist? Zones of Interest

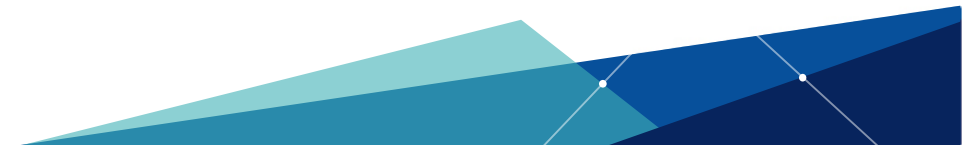
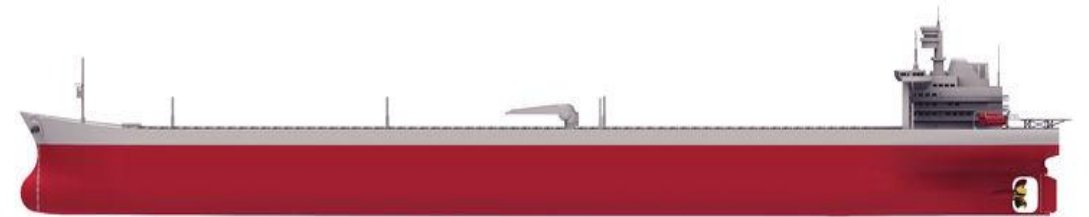
- Height of eye and radar range
- Vessel size
- Vessel speed and manoeuvrability
- Visibility
- Location
- Under keel clearance.





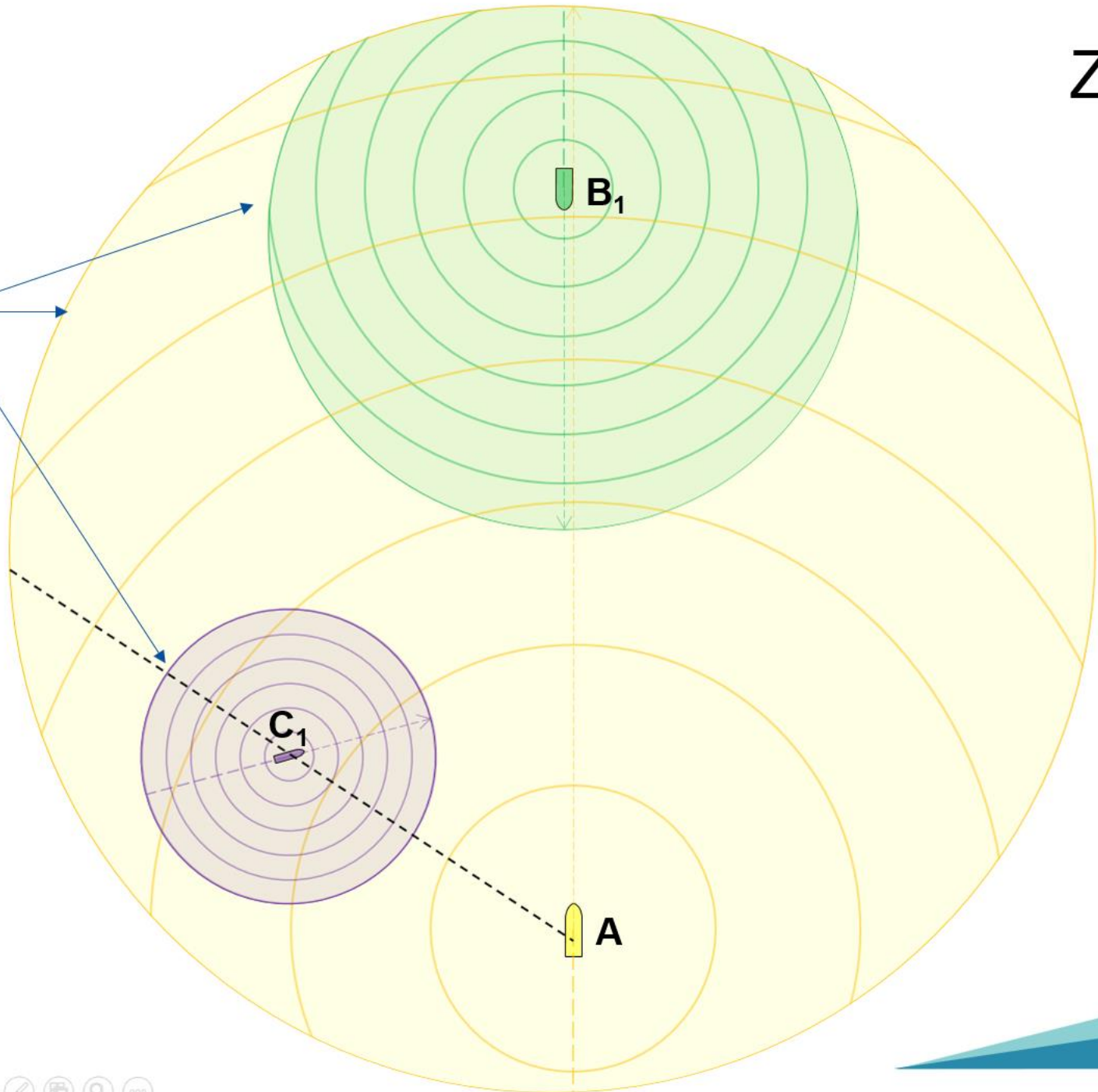
When does a risk of collision exist? Zones of Interest

- Height of eye and radar range
- Vessel size
- Vessel speed and manoeuvrability
- Visibility
- Location
- Under keel clearance.





Radar Ranges



Zones of Interest

A & B = Head-on situation

A & C = Crossing situation

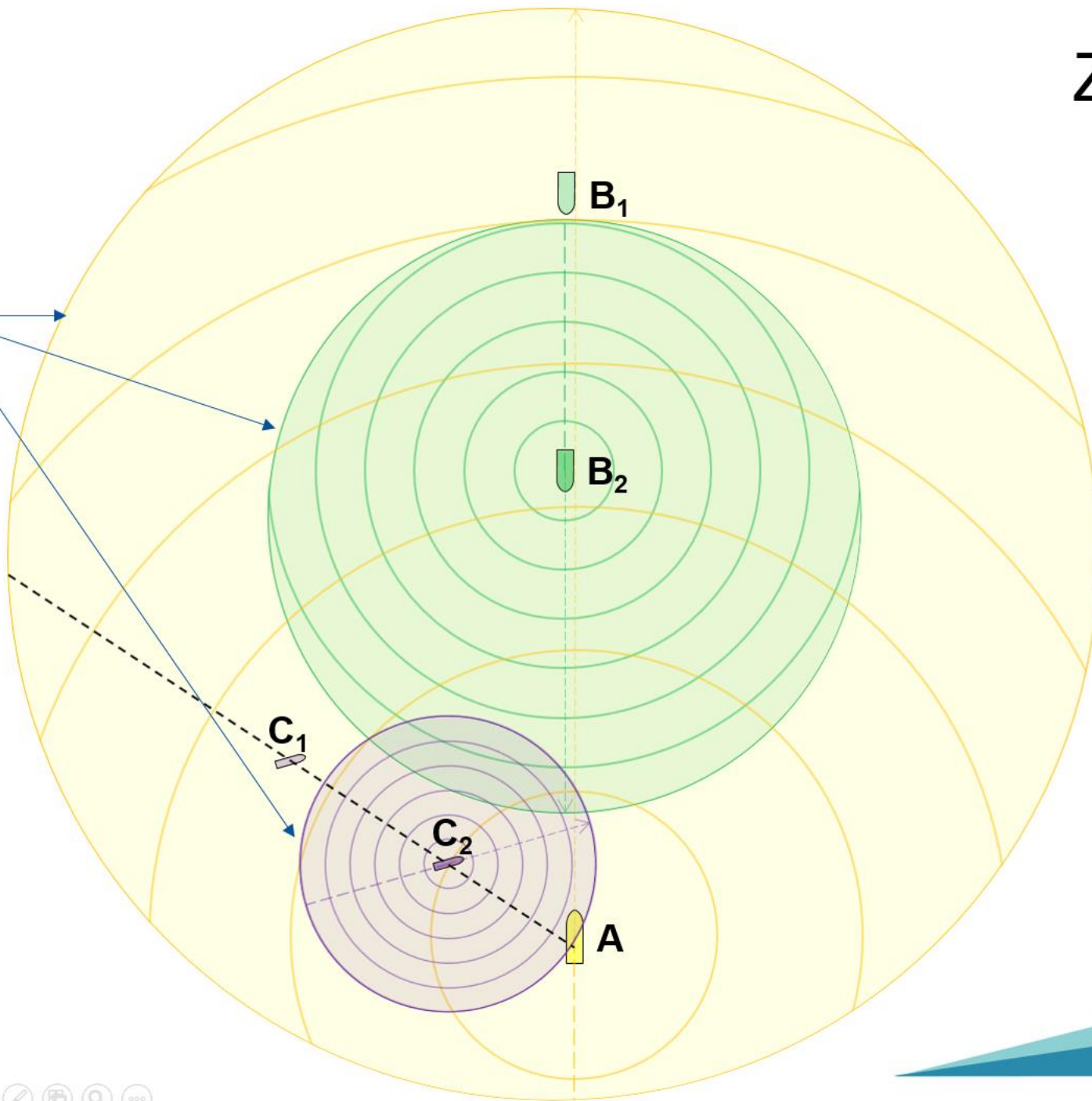
B & C = No risk of collision



Zones of Interest



Radar Ranges



Probability

A = Stood-on for C
= Altered starboard for B & C

B = Did nothing

C = Did nothing





Electronic Evidence





How Electronic Evidence Works: Modern Bridge



CCTV

AIS

Digital Heading

GPS

VDR Panel

ECDIS

Paper Chart



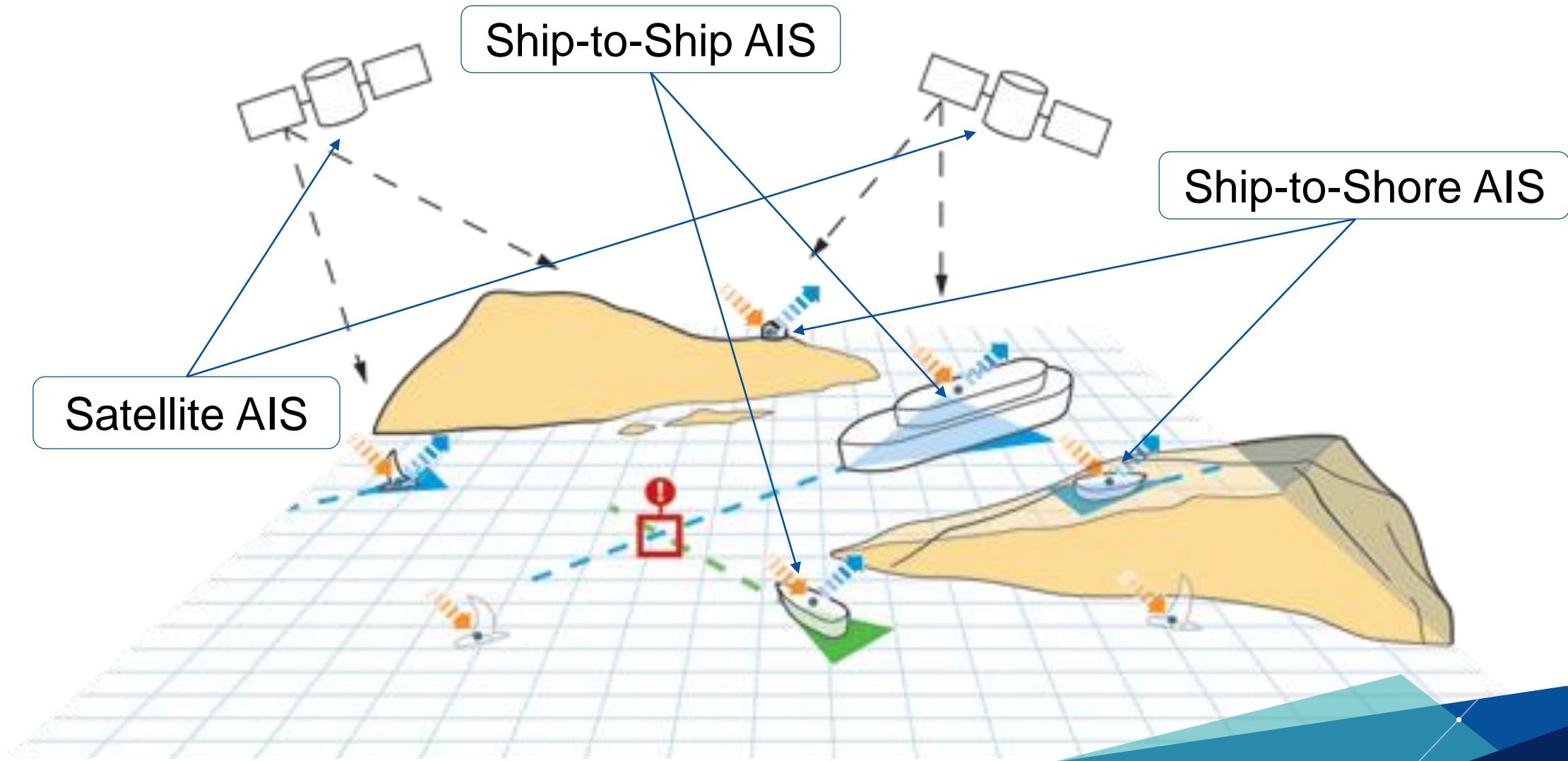
How it works: Sources of Electronic Evidence

- Automatic Identification System (AIS)
- Electronic Chart Display and Information System (ECDIS)
- Voyage Data Recorder (VDR)
- Audio, Video and Still Images.





How it works: Automatic Identification System (AIS)





How it works: Automatic Identification System (AIS)

- Vessels over 300 GT (Type A)
- Ship-to-ship situational awareness and manage controlled water space
- Public broadcast VHF transponder device and available open source
- Transmission frequency:
 - **Static:** Every 6 minutes - Vessel details
 - **Dynamic:** Dependant on speed and course - Time, position, course and speed
 - **Voyage Related:** Every 6 minutes - Vessel draft, POB, haz cargo and where bound.



How it works: Automatic Identification System (AIS)

AIS Type A Reporting intervals of Dynamic Information

Manoeuvring Status

Interval

Ships at anchor or moored and not faster than 3 knots

3 minutes

Ships at anchor or moored and faster than 3 knots

10 seconds

Ship 0-14 knots

10 seconds

Ship 0-14 knots and changing course

3 $\frac{1}{3}$ seconds

Ship 14-23 knots

6 seconds

Ship 14-23 knots and changing course

2 seconds

Ship >23 knots

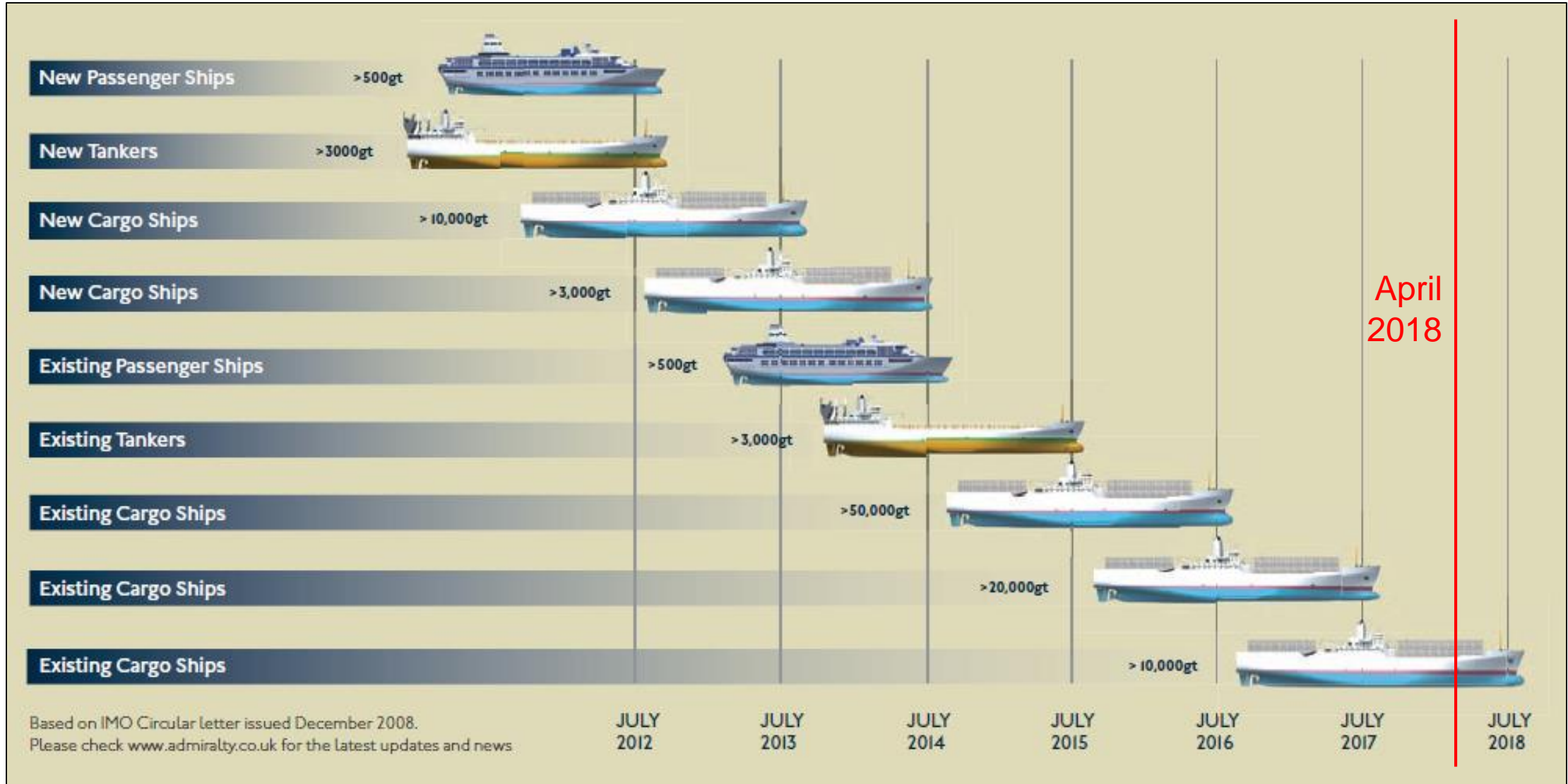
2 seconds

Ship >23 knots changing course

2 seconds



How it works: ECDIS Roll-out and Principle Features





How it works: ECDIS Roll-out and Principle Features

- Electronic chart displaying ‘real-time’ position, course and speed

- Undertakes complex functions to improve ‘situational awareness’:

- Appraisal, planning, execution and monitoring

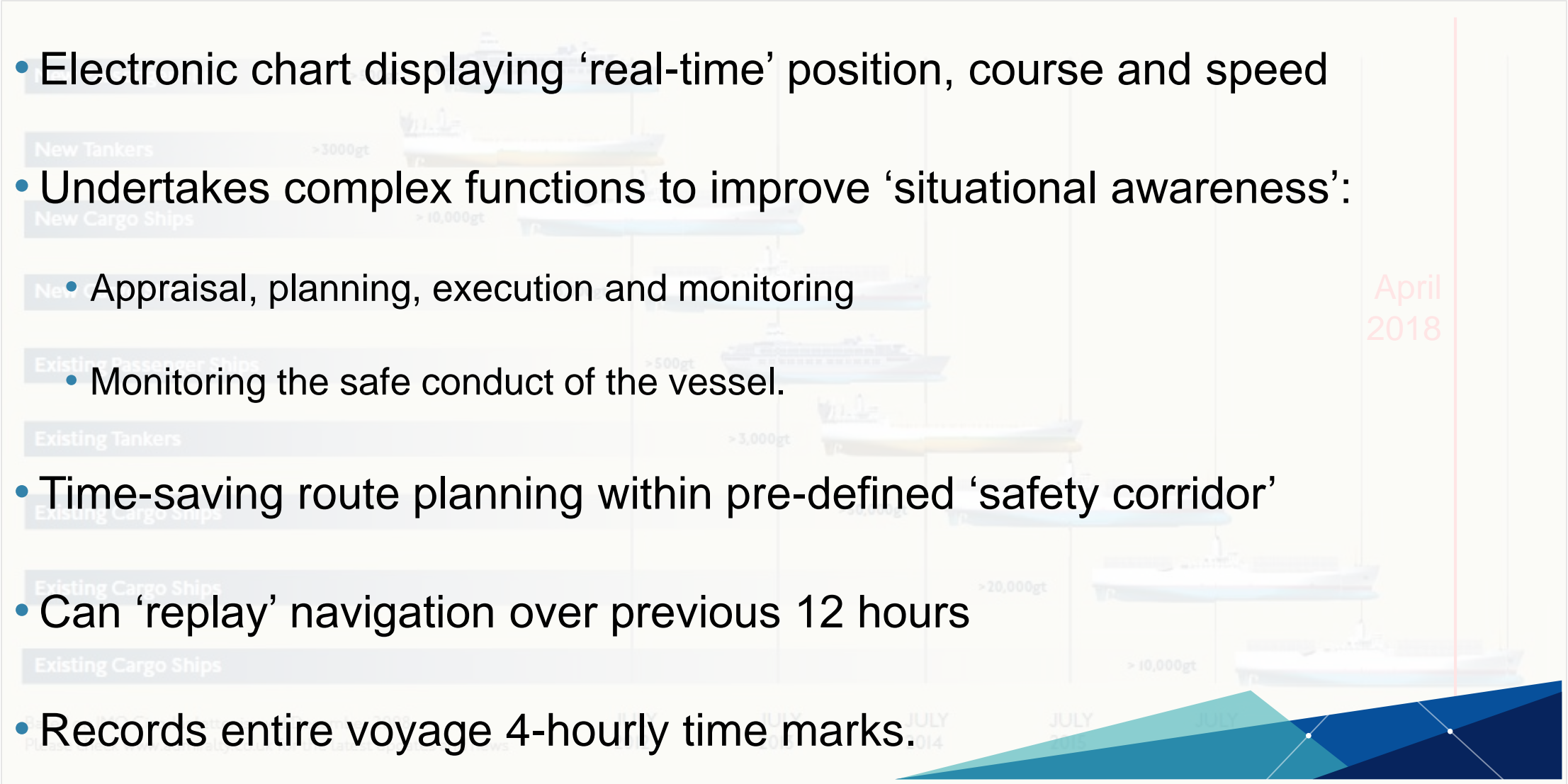
- Monitoring the safe conduct of the vessel.

- Time-saving route planning within pre-defined ‘safety corridor’

- Can ‘replay’ navigation over previous 12 hours

- Records entire voyage 4-hourly time marks.

April
2018



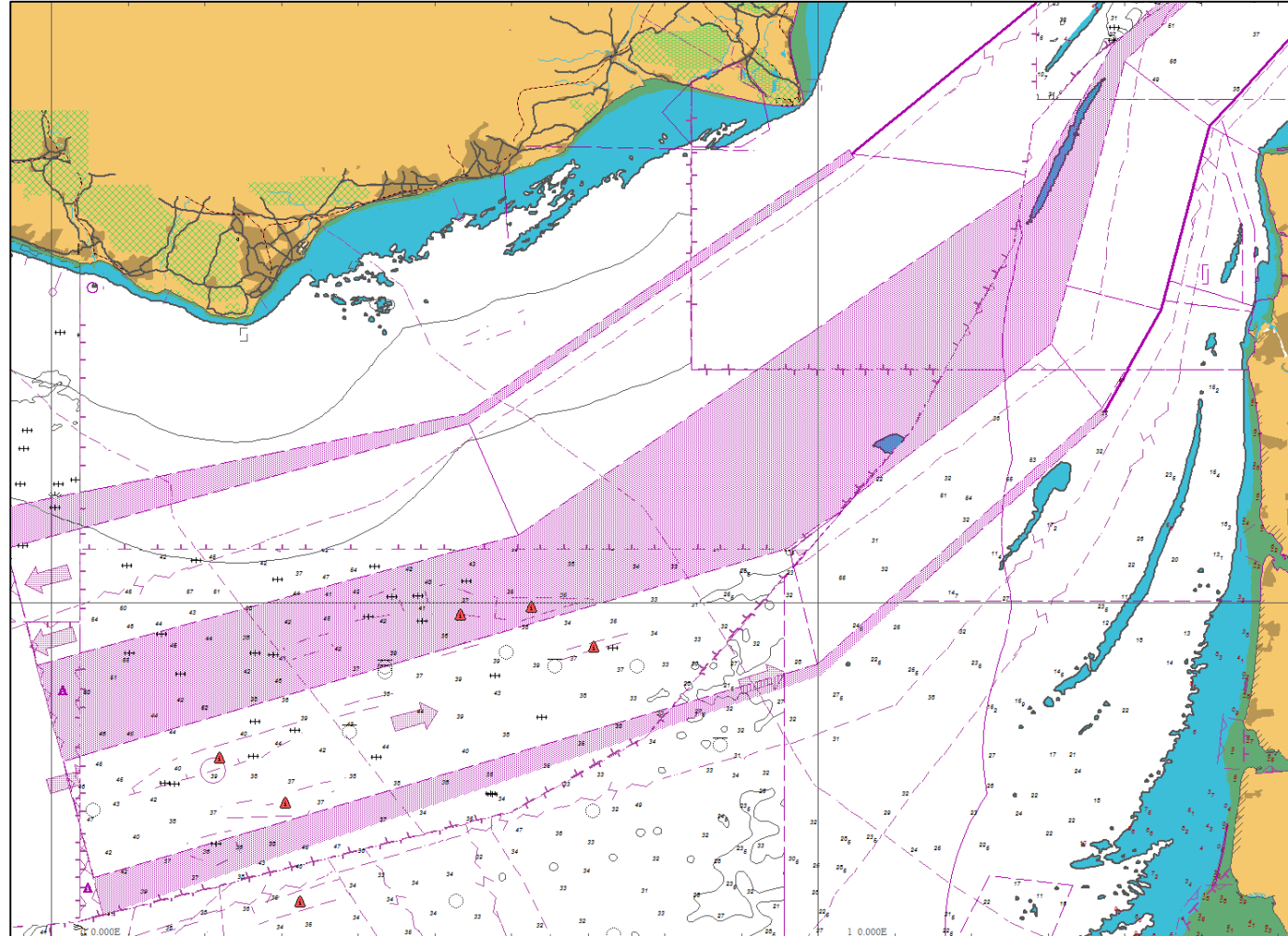


How it works: ECDIS [PlayStation Generation Y]

Life before ECDIS... the Paper Chart

Dover Strait – West

Actually, a raster image that looks like a paper chart





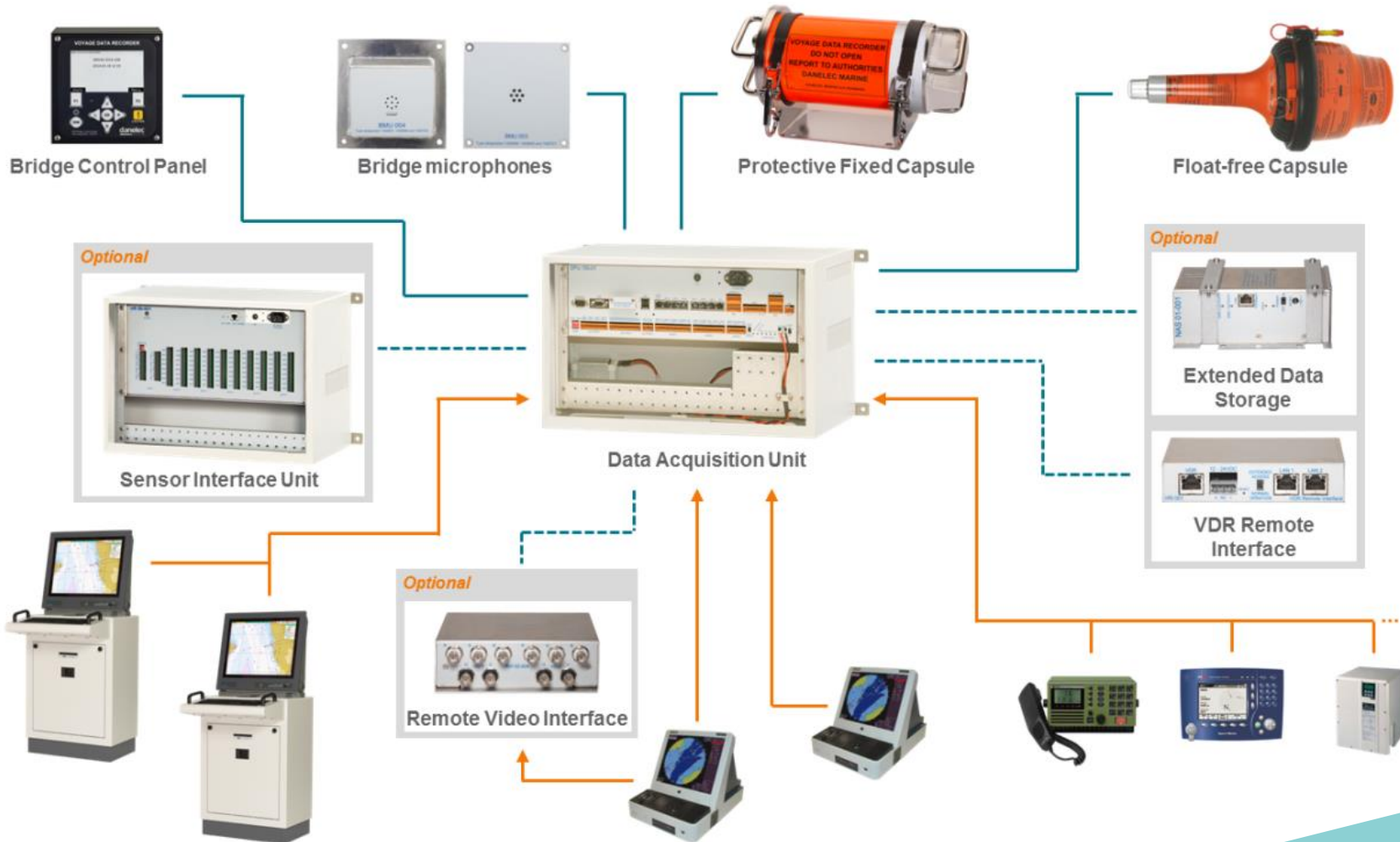
How it works: ECDIS [PlayStation Generation Y]

The image shows a screenshot of the ECDIS (Electronic Chart Display and Information System) interface. The interface is divided into several sections:

- ECDIS Menu:** Located on the left side, it contains various settings and data. Key information includes:
 - Internal Clock: 10 AUG 2016 01:58:09 UTC
 - ENC Category: Standard
 - Depth: [m]
 - Status: Better scale available
 - Display: North Up, Range 24 NM, REF CCRP
 - Heading & Speed: HDG 230.2°, STW 18.1 kn, COG 230.3°, SOG 18.1 kn, Set 337.8°, Drift 0.0 kn
 - Position: 51°00.195' N, 001°19.766' E
 - REF: Ground, Vector 12 min
 - Track: Set 230.6°, 2.00 NM; Next 254.5°, 2.00 NM
 - Route: Hamburg - Lissabon
 - Alerts: No Unacknowledged Alerts
 - Depth Sensor: DBK 17.1 m
- Safety contour:** A dashed line on the chart representing a safety boundary.
- Safety corridor:** A shaded area representing a safe passage route.
- Own vessel GPS and vector:** A red arrow and circle representing the vessel's current position and heading.
- Other vessel AIS and vector:** Various colored symbols and arrows representing other vessels in the area.
- Tide vectors:** Small arrows on the chart indicating tidal currents.



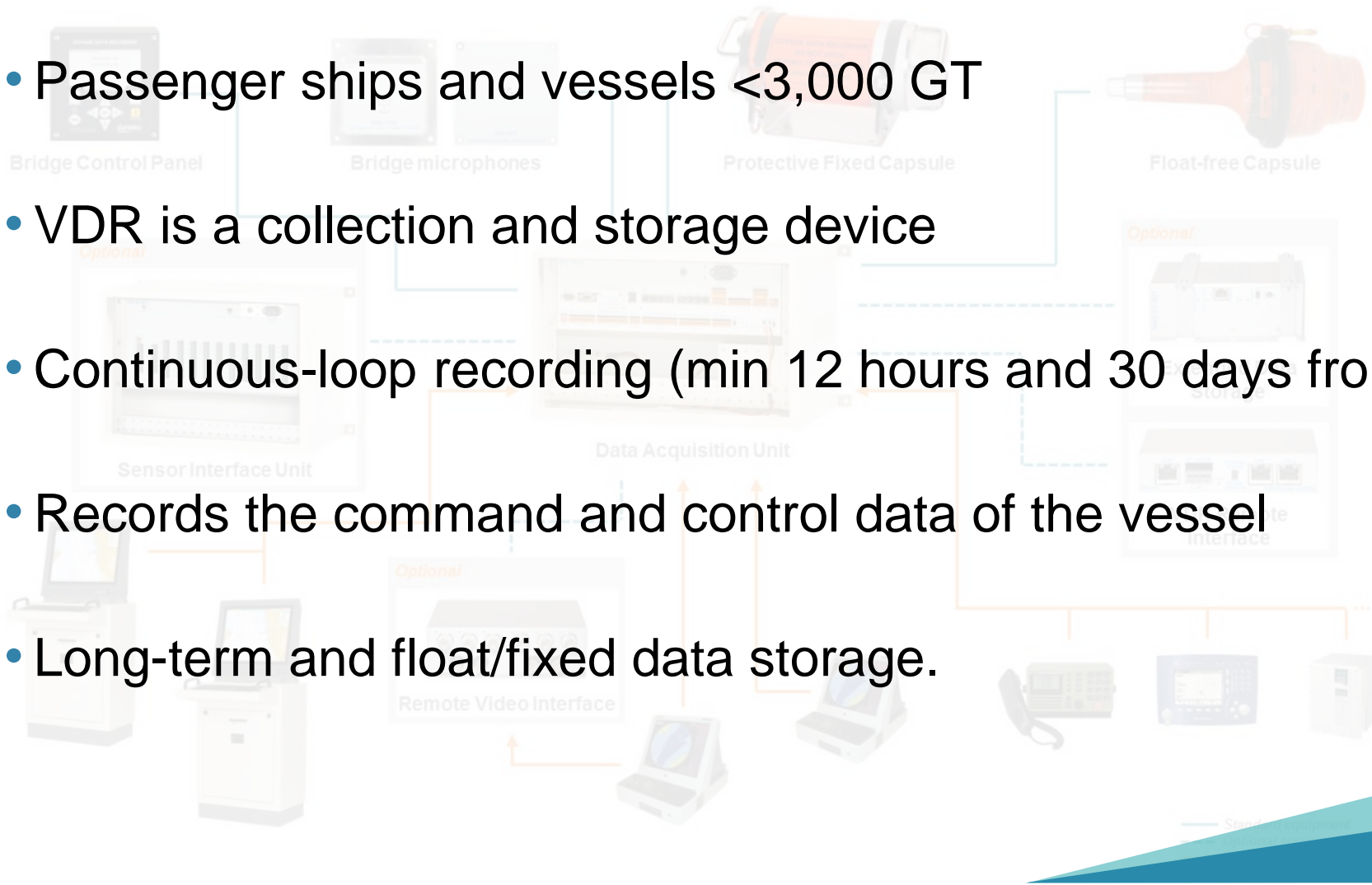
How it works: Voyage Data Recorder (VDR)





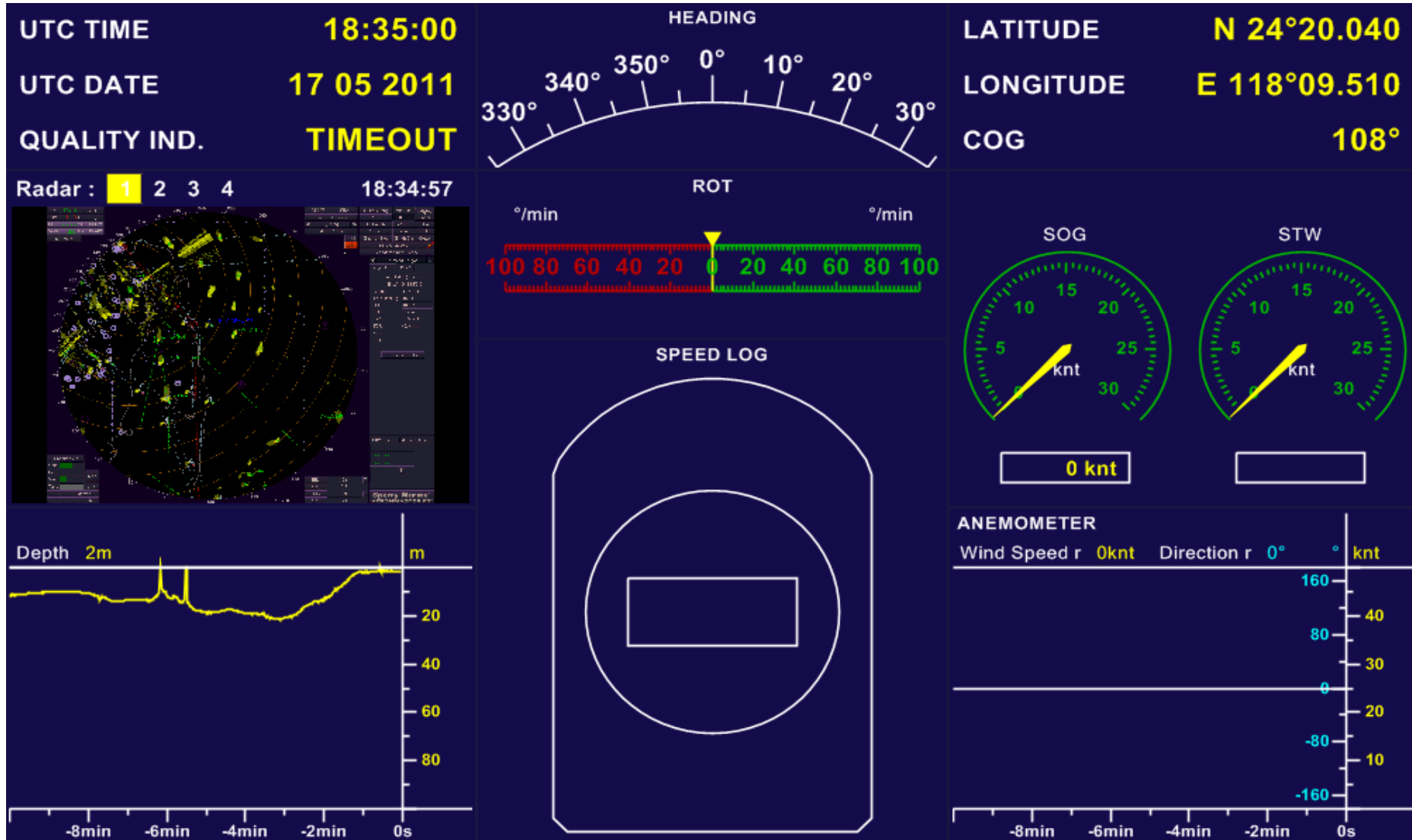
How it works: Voyage Data Recorder (VDR)

- Passenger ships and vessels <3,000 GT
- VDR is a collection and storage device
- Continuous-loop recording (min 12 hours and 30 days from 01 Jul 2014)
- Records the command and control data of the vessel
- Long-term and float/fixed data storage.





How it works: VDR Replay Software





Casualty Investigation and Accident Analysis





Investigating Failures in Situational Awareness

- Groundings and collisions: failure of 'situational awareness'
- Causation: forensic analysis of electronic evidence
- Validate: compare 'contemporaneous' evidence





2-D MADAS (Marine Accident Data Analysis Suite)

- Developed by Avenca Ltd for UK MAIB and US NTSB.
- The software can:
 - Display multiple tracks
 - Extract and use AIS and/or VDR data
 - Use audio tracks
 - Display charts and overlays
 - Display various media including radar overlay
 - Display ship shapes.

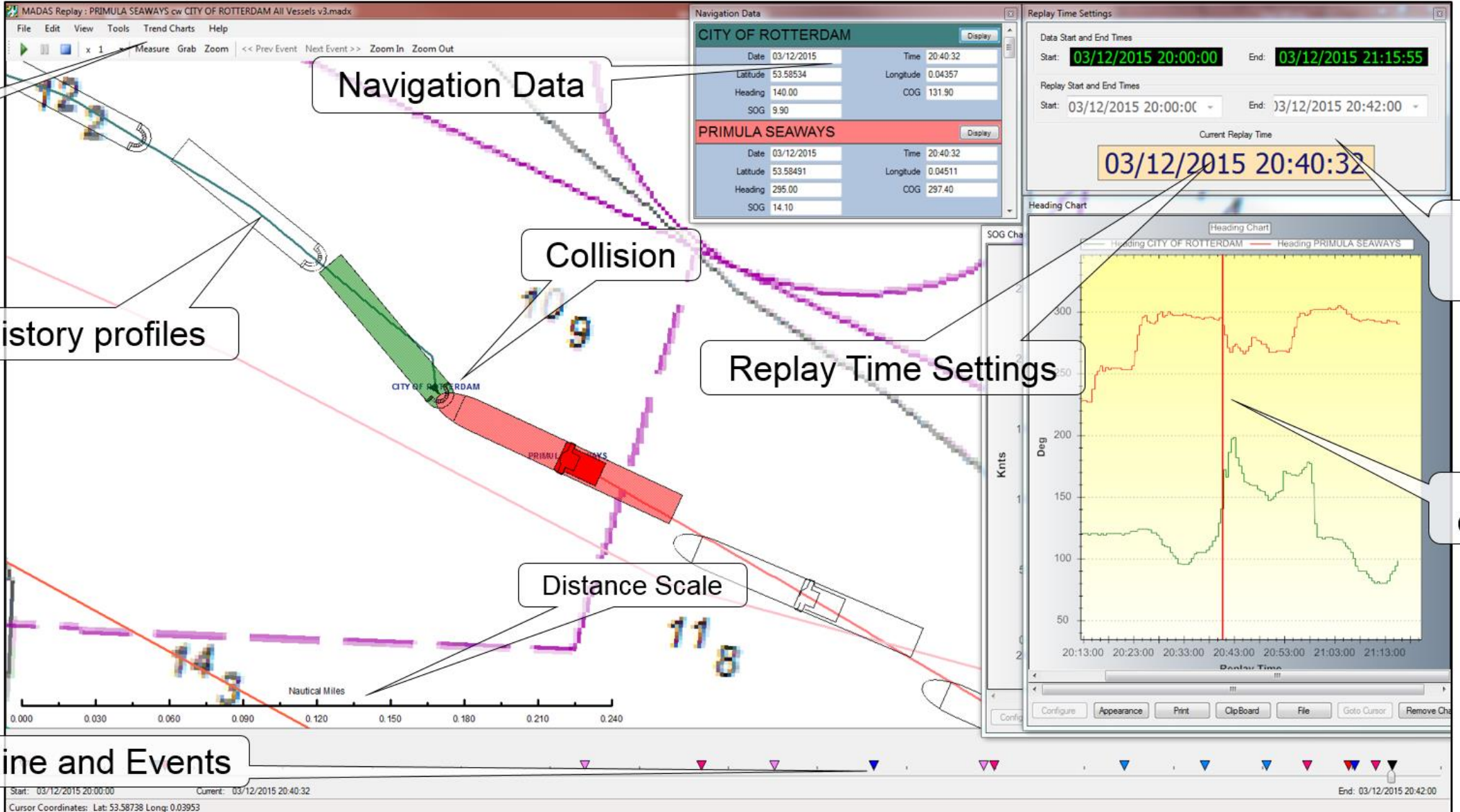


avenca





Sample MADAS Replay Software



Menu Bar

Navigation Data

03/12/2015 20:40:32

Trend Charts

Collision

Replay Time Settings

Time Cursor

History profiles

Distance Scale

Timeline and Events

LOC MADAS Replay Software

The screenshot displays the LOC MADAS Replay Software interface. The main window shows a radar overlay on a map with various tracks and targets. A menu bar is visible at the top left. A 'Replay Time Settings' panel is located in the top right, showing data start and end times (20/08/2017 18:59:08 to 21:30:01) and a current replay time of 20/08/2017 21:04:31. A 'Navigation Data' panel on the right lists details for several vessels: GUANG ZHOU WAN, LONG HU SAN, HYUNDAI GLOBAL, KEN SAN, and CONTSHIP BOX. A 'Distance Scale' is shown at the bottom left, and a 'Timeline and Events' bar is at the bottom. A 'Compass Graticule' is centered on the map. Callouts identify the 'Menu Bar', 'Radar overlay', 'Radar targets with AIS overlay', 'Track with history', 'Compass Graticule', 'Navigation Data', 'Distance Scale', and 'Timeline and Events'.

Menu Bar

Radar overlay

Radar targets with AIS overlay

Track with history

Compass Graticule

Navigation Data

Distance Scale

Timeline and Events

Replay Time Settings

Navigation Data

| GUANG ZHOU WAN | |
|----------------|------------|
| Date | 20/08/2017 |
| Time | 21:04:31 |
| Latitude | 1.44201 |
| Longitude | 104.48611 |
| Heading | 223.11 |
| COG | 223.11 |
| SOG | 9.08 |

| LONG HU SAN | |
|-------------|------------|
| Date | 20/08/2017 |
| Time | 21:04:31 |
| Latitude | 1.44835 |
| Longitude | 104.49761 |
| Heading | 233.08 |
| COG | 233.08 |
| SOG | 8.55 |

| HYUNDAI GLOBAL | |
|----------------|------------|
| Date | 20/08/2017 |
| Time | 21:04:31 |
| Latitude | 1.45815 |
| Longitude | 104.51436 |
| Heading | 230.19 |
| COG | 230.19 |
| SOG | 11.25 |

| KEN SAN | |
|-----------|------------|
| Date | 20/08/2017 |
| Time | 21:04:31 |
| Latitude | 1.46479 |
| Longitude | 104.50984 |
| Heading | 226.62 |
| COG | 226.62 |
| SOG | 8.91 |

| CONTSHIP BOX | |
|--------------|------------|
| Date | 20/08/2017 |
| Time | 21:04:31 |
| Latitude | 1.46485 |
| Longitude | 104.49985 |
| Heading | 229.91 |
| COG | 229.91 |
| SOG | 9.41 |

Start: 20/08/2017 21:00:00 Current: 20/08/2017 21:04:31 End: 20/08/2017 21:30:01

Cursor Coordinates: Lat: 1.43792 Long: 104.36989



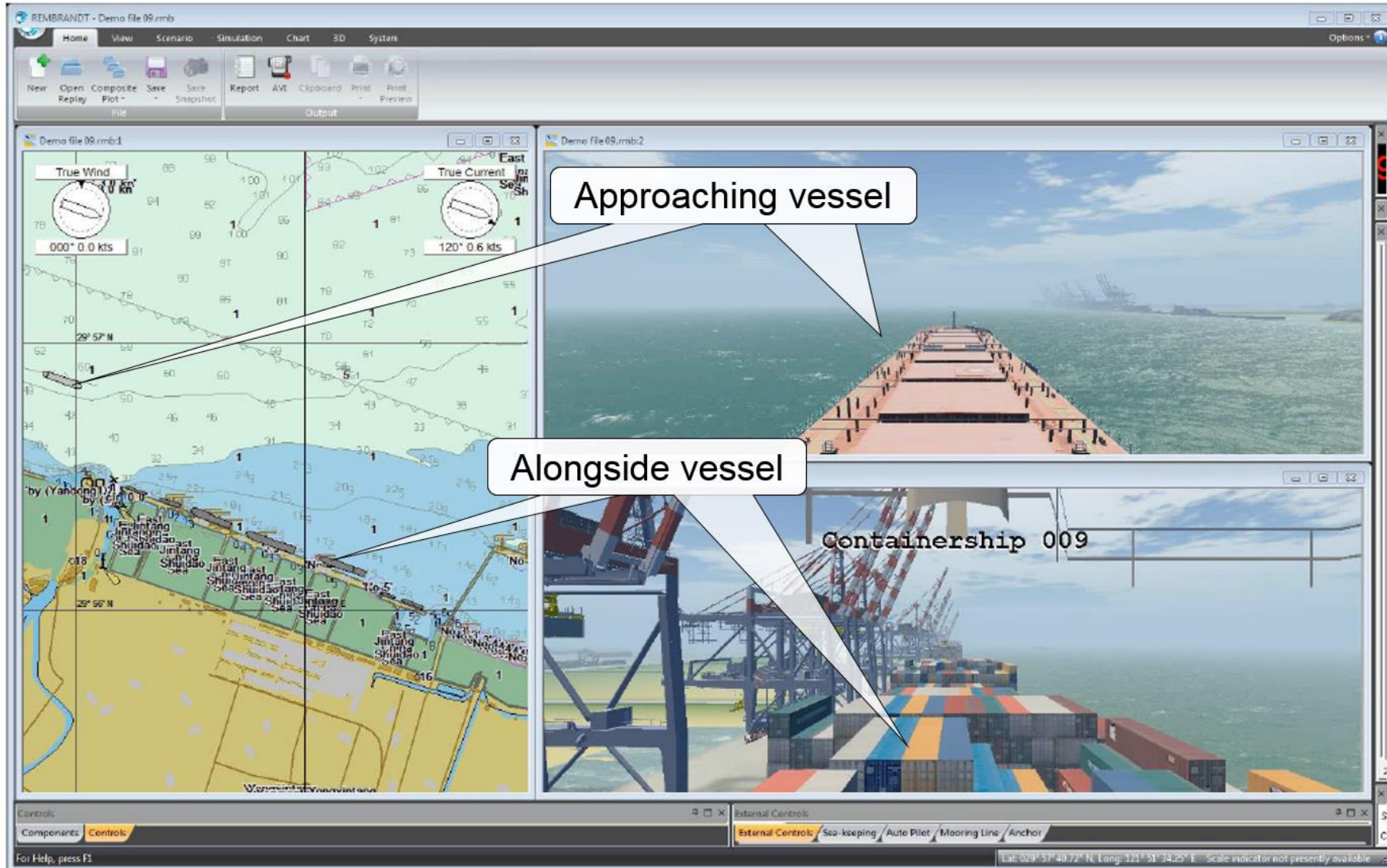
3-D REMBRANDT (Real-time Manoeuvring, Berthing and Training)


- Developed by BMT and used by many shipowners, pilots and port authorities
- The software can model:
 - Recreate environmental conditions
 - Use raster and vector ENC charts to give bathymetric representation
 - Visual topography with additional library or customer specified objects
 - Large vessel database or tailored hull designs and propulsion configurations
 - Imports same electronic data as MADAS.





REMBRANDT – Collision analysis



 LOC REMBRANDT – Visual scene with photo texturing



Visual scene with photo texturing

Actual photograph





[Traditional] Casualty Investigation and Litigation

- Attend casualty, interview crew and take statements
- Collect contemporaneous [and digital] evidence
- Determine ‘angle of blow’ in collisions
- Determine ‘type and location of damage’ in groundings
- Disclose documentation [including digital evidence]
- Engage experts if no agreement
- Proceed to trial.





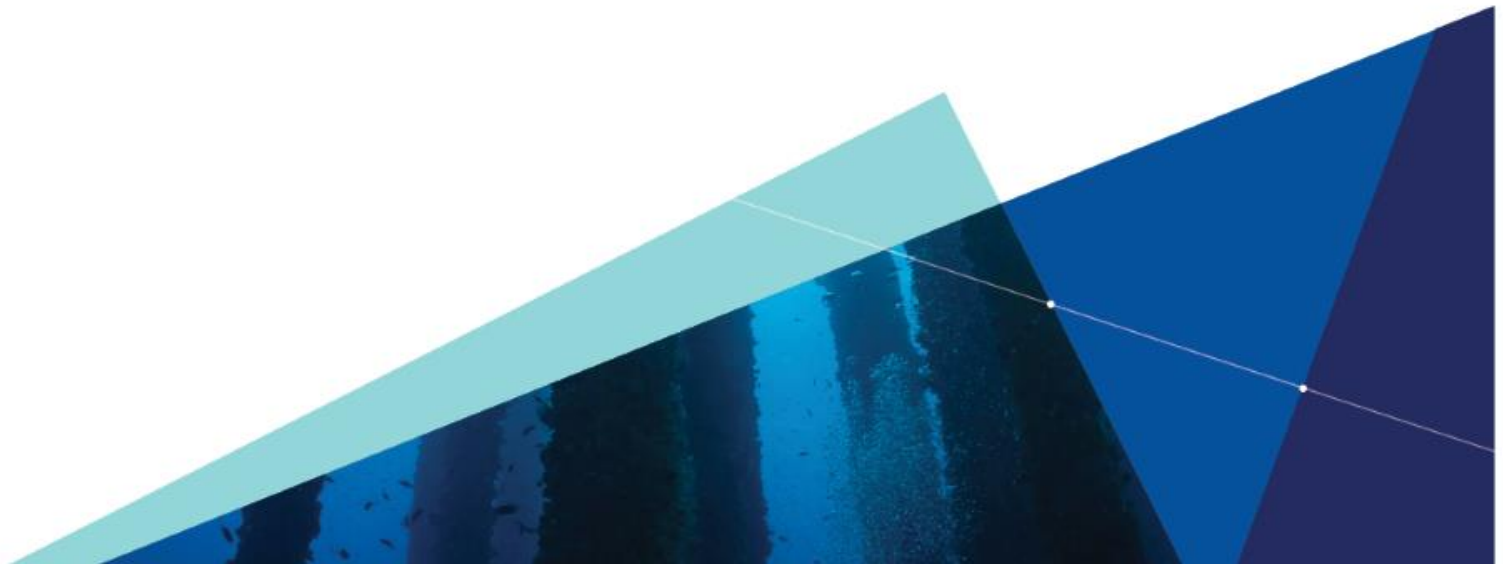
[Modern] Accident Analysis

- Undertake accident analysis using electronic evidence
- Validate contemporaneous evidence
- Incontrovertible evidence leads to:
 - Agreed set of facts, and
 - Causation
- Parties agree 'liability' and 'costs', often without litigation and trial.





Case Studies



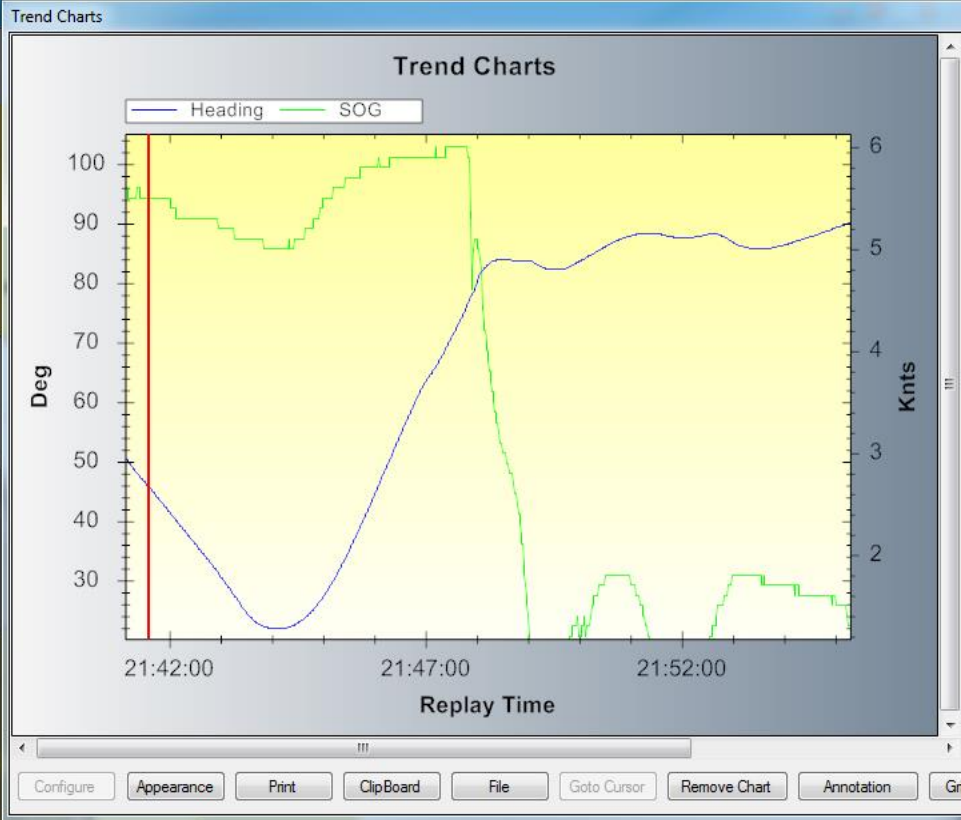
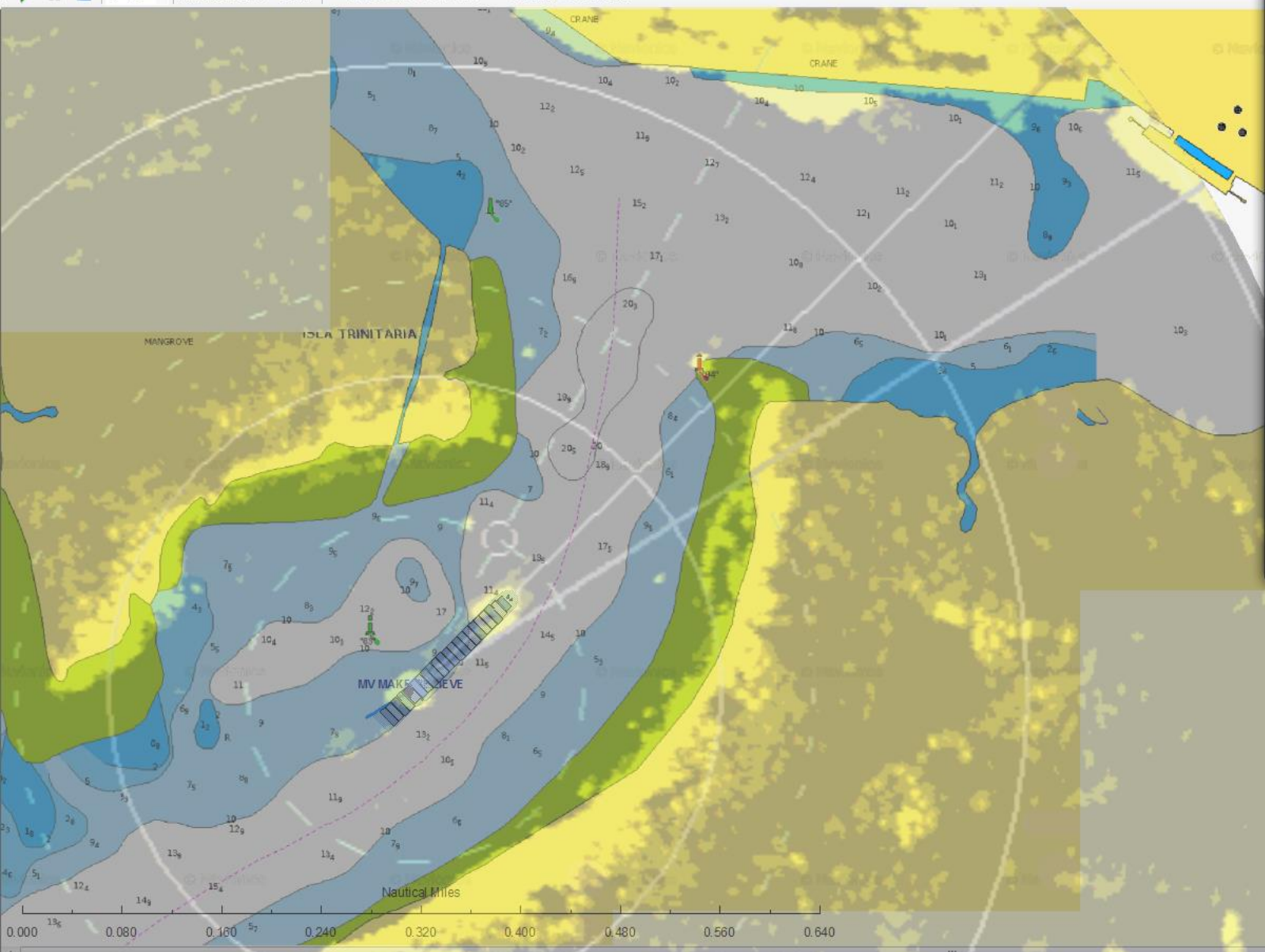


Case 1: MV MAKE BELIEVE Allision with the Quayside

- 5th April 2010, Never Never Land
- Full VDR with radar overlay and audio
- Daylight in favourable conditions
- MV MAKE BELIEVE passes through narrow channel to approach berth
- No tugs in attendance.

(Screenshots i.e. not video)





Replay Time Settings

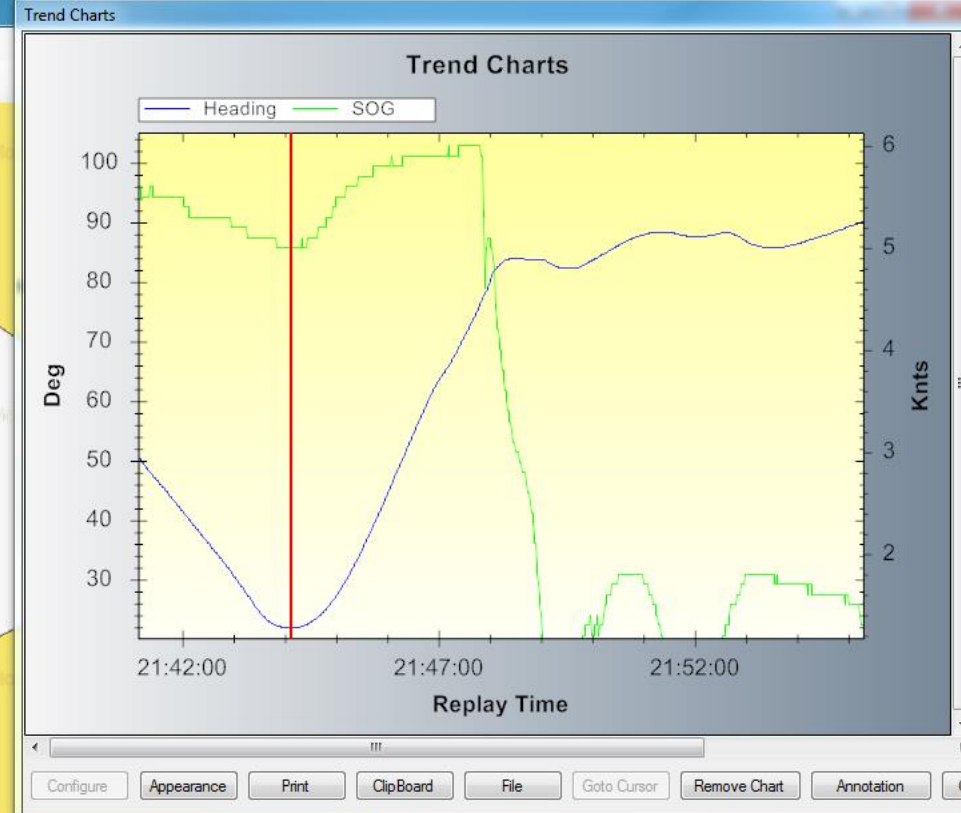
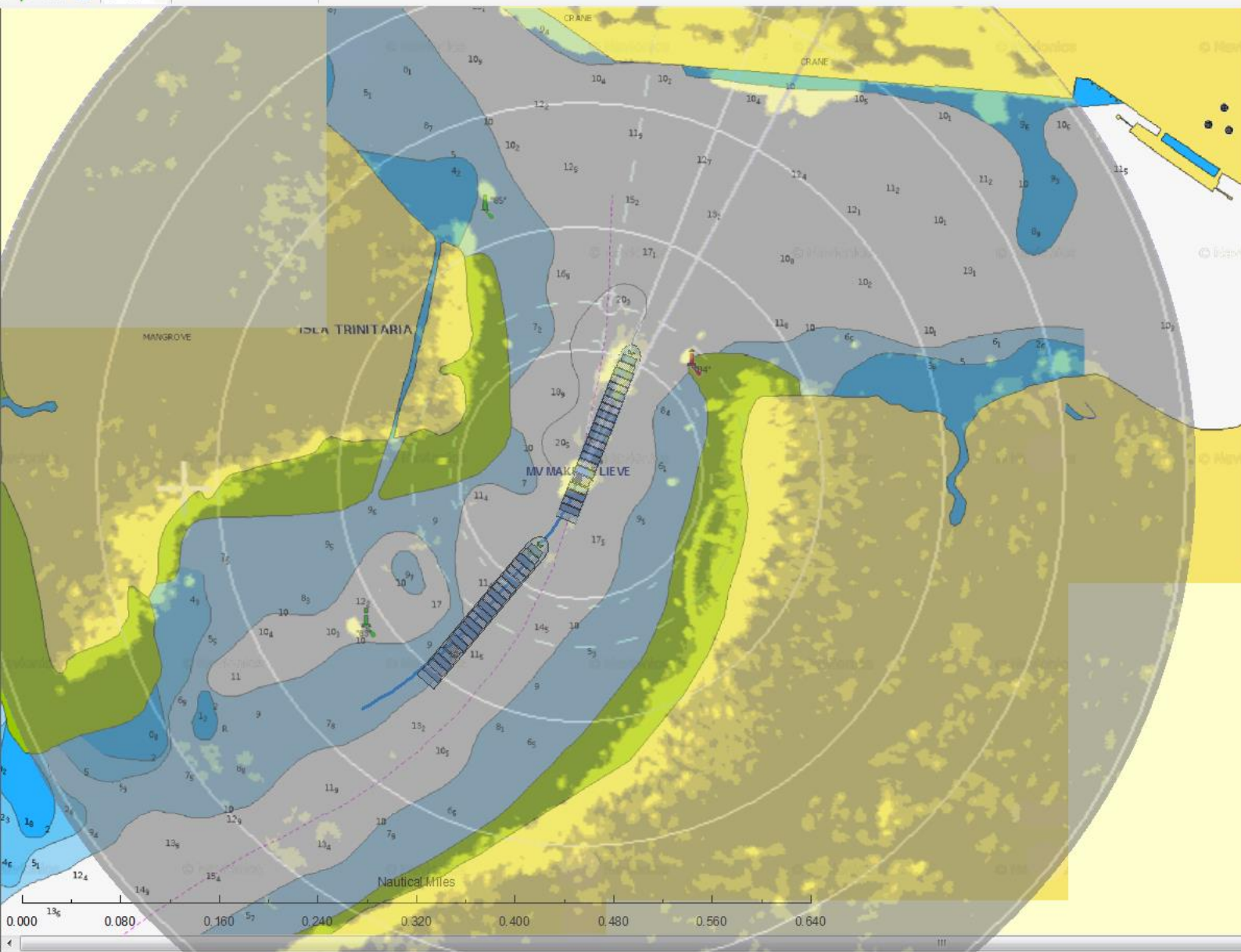
Data Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Replay Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Current Replay Time
05/04/2010 21:41:34

Navigation Data

| MV MAKE BELIEVE | | | |
|-----------------|------------|-----------|-----------|
| Date | 05/04/2010 | Time | 21:41:34 |
| Latitude | -2.29163 | Longitude | -79.90797 |
| Heading | 046.00 | COG | 055.30 |
| SOG | 5.50 | LOG | 6.88 |



Replay Time Settings

Data Start and End Times
 Start: **05/04/2010 21:41:07** End: **05/04/2010 22:00:35**

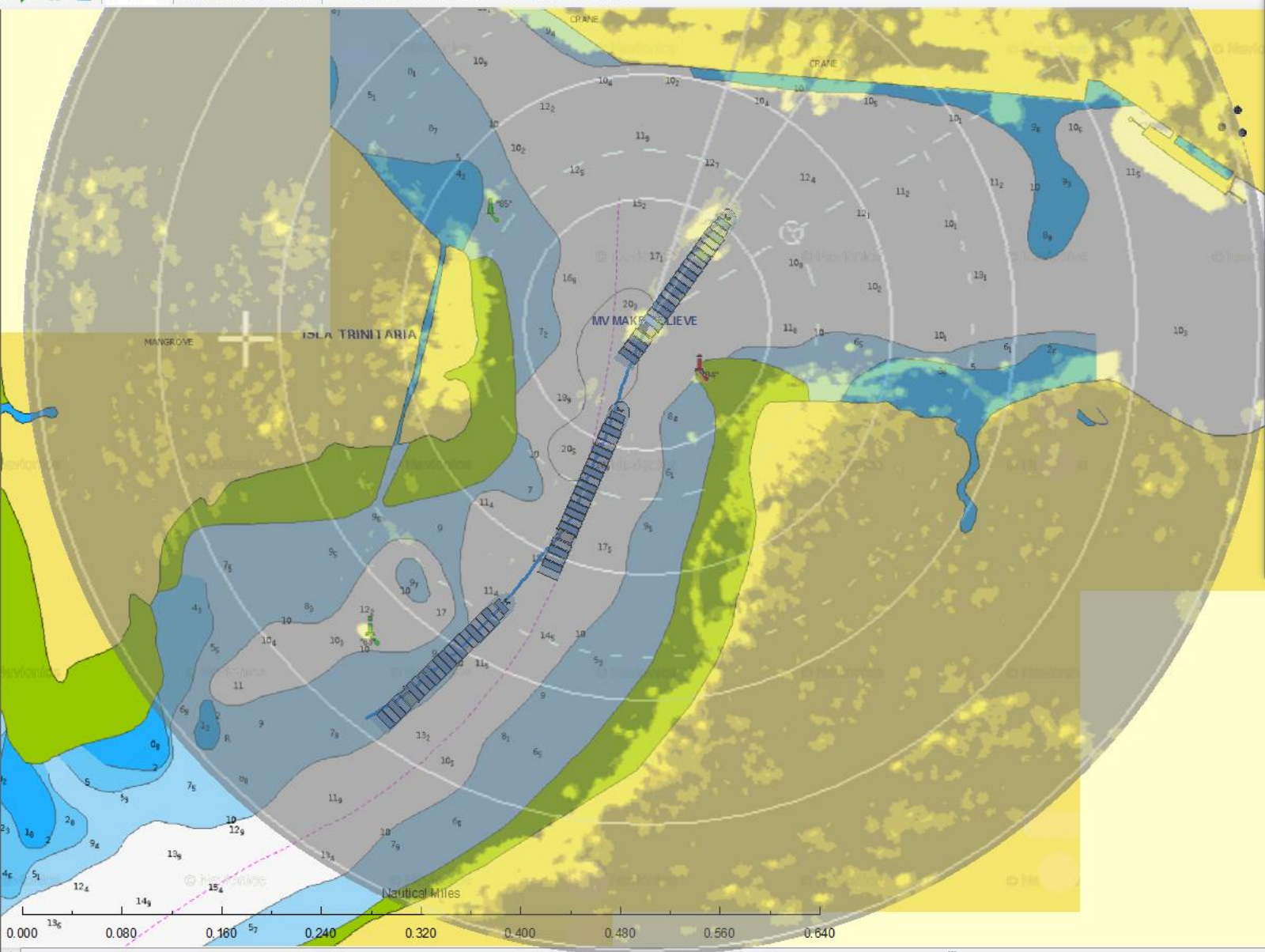
Replay Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Current Replay Time

05/04/2010 21:44:05

Navigation Data

| MV MAKE BELIEVE | | Audio | Display |
|-----------------|------------|-----------|-----------|
| Date | 05/04/2010 | Time | 21:44:05 |
| Latitude | -2.28890 | Longitude | -79.90564 |
| Heading | 021.90 | COG | 025.60 |
| SOG | 5.00 | LOG | 6.62 |



Replay Time Settings

Data Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

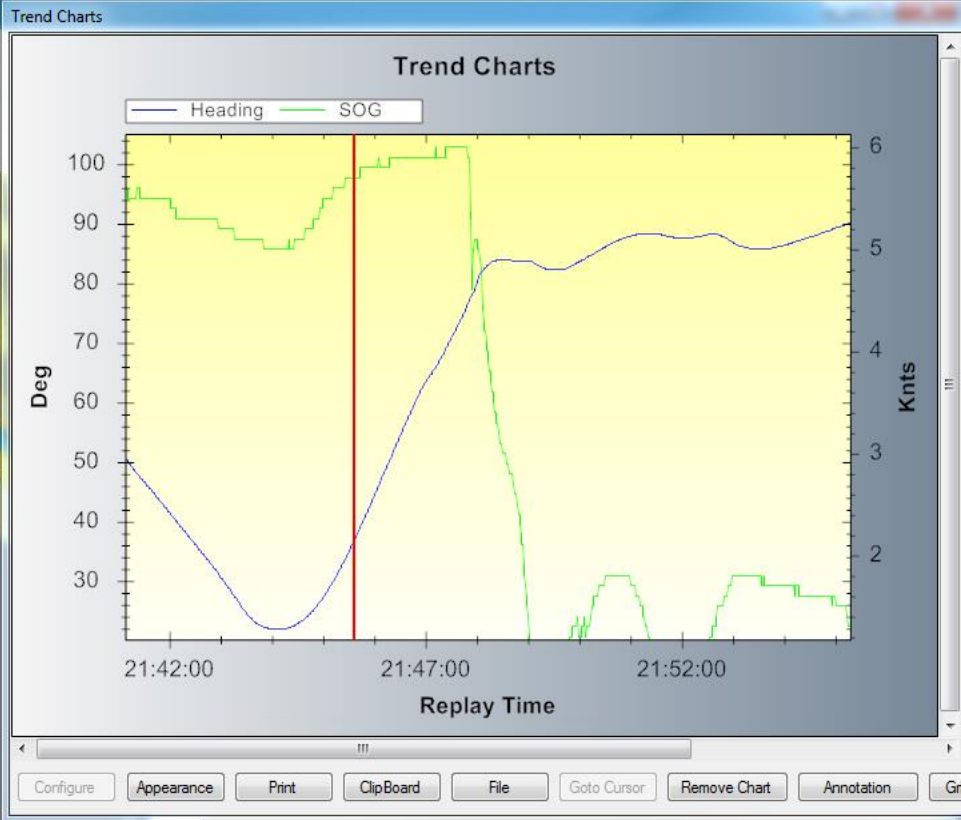
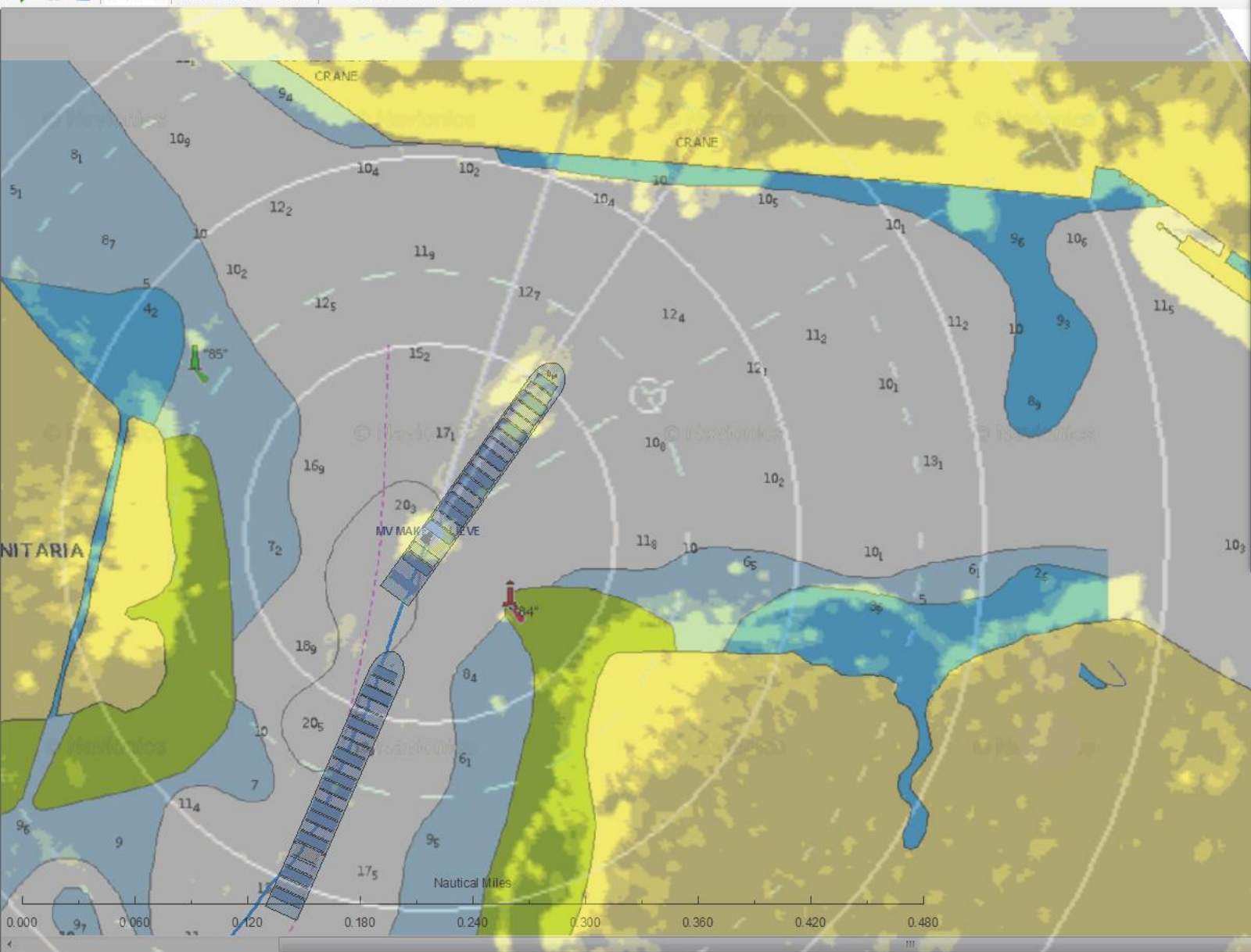
Replay Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Current Replay Time
05/04/2010 21:45:34

Navigation Data

| MV MAKE BELIEVE | | | |
|-----------------|------------|-----------|-----------|
| Date | 05/04/2010 | Time | 21:45:34 |
| Latitude | -2.28682 | Longitude | -79.90483 |
| Heading | 036.10 | COG | 021.50 |
| SOG | 5.70 | LOG | 7.34 |

Buttons: Audio Display



Replay Time Settings

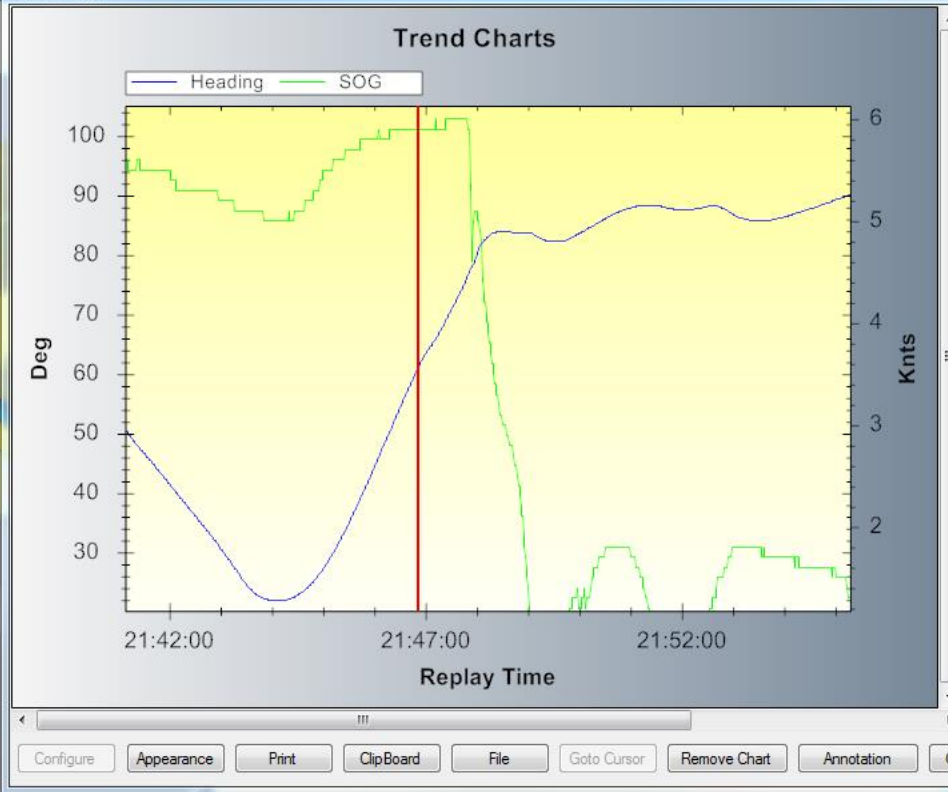
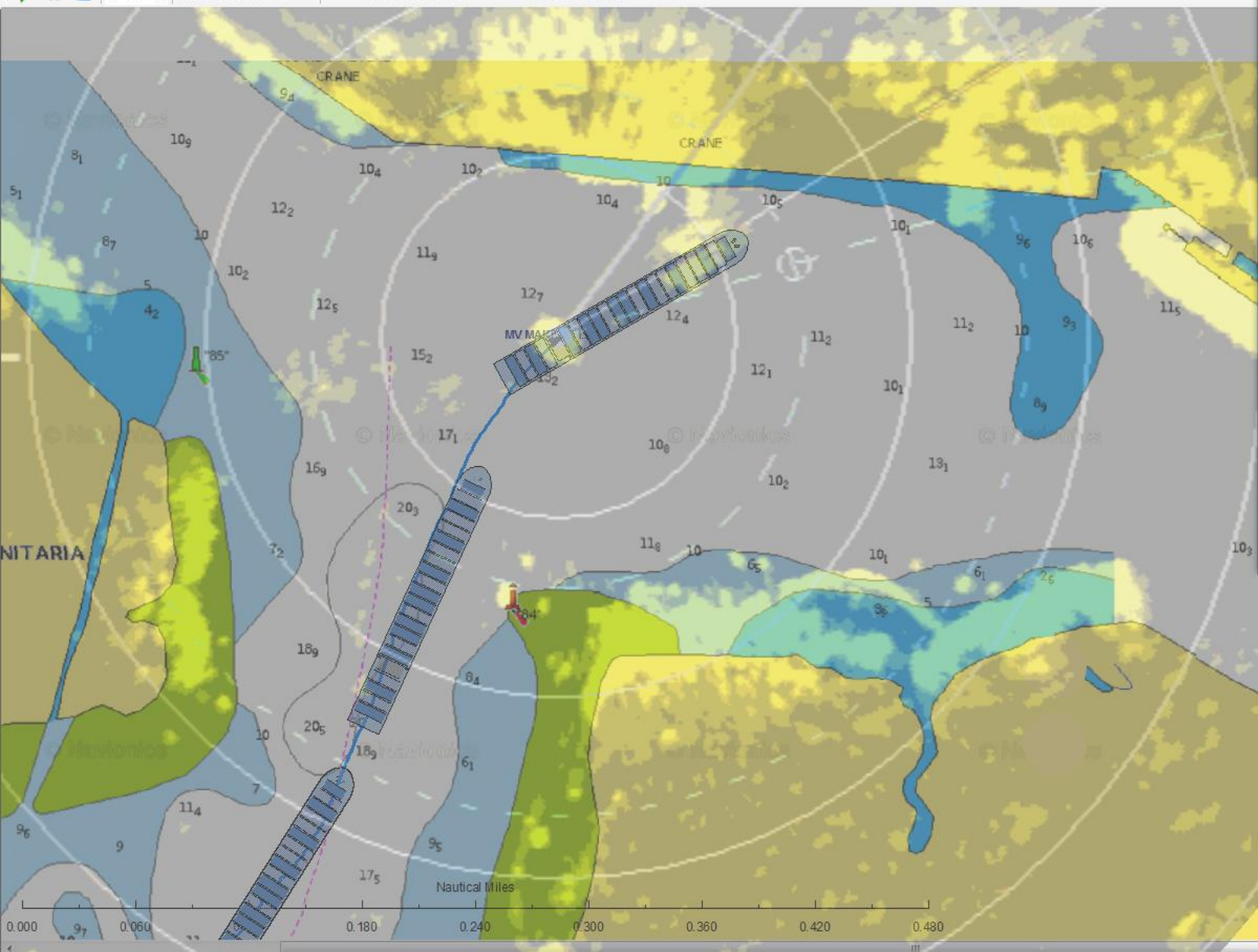
Data Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Replay Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Current Replay Time
05/04/2010 21:45:34

Navigation Data

| MV MAKE BELIEVE | | | |
|-----------------|------------|-----------|-----------|
| Date | 05/04/2010 | Time | 21:45:34 |
| Latitude | -2.28682 | Longitude | -79.90483 |
| Heading | 036.10 | COG | 021.50 |
| SOG | 5.70 | LOG | 7.34 |



Replay Time Settings

Data Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Replay Start and End Times
 Start: 05/04/2010 21:41:07 End: 05/04/2010 22:00:35

Current Replay Time
05/04/2010 21:46:49

Navigation Data

| MV MAKE BELIEVE | |
|-----------------|------------|
| Date | 05/04/2010 |
| Time | 21:46:49 |
| Latitude | -2.28508 |
| Longitude | -79.90372 |
| Heading | 060.40 |
| COG | 043.80 |
| SOG | 5.90 |
| LOG | 7.58 |



Case 2: PRIMULA SEAWAYS c/w CITY OF ROTTERDAM

- Date 3rd December 2015, Humber Estuary, Hull, England
- Open-Source Terrestrial AIS, no VDR
- Dawn, poor visibility, and very high wind and sea
- CITY OF ROTTERDAM pilot embarked outbound
- PRIMULA SEAWAYS pilot exemption inbound.



City of Rotterdam uncontrolled swing to starboard toward mid-channel operating engines astern

City of Rotterdam continues starboard turn

Primula Seaways uncontrolled swing to port operating engines astern

Navigation Data

| CITY OF ROTTERDAM | | | |
|-------------------|------------|-----------|----------|
| Date | 03/12/2015 | Time | 20:40:32 |
| Latitude | 53.58534 | Longitude | 0.04357 |
| Heading | 140.00 | COG | 131.90 |
| SOG | 9.90 | | |

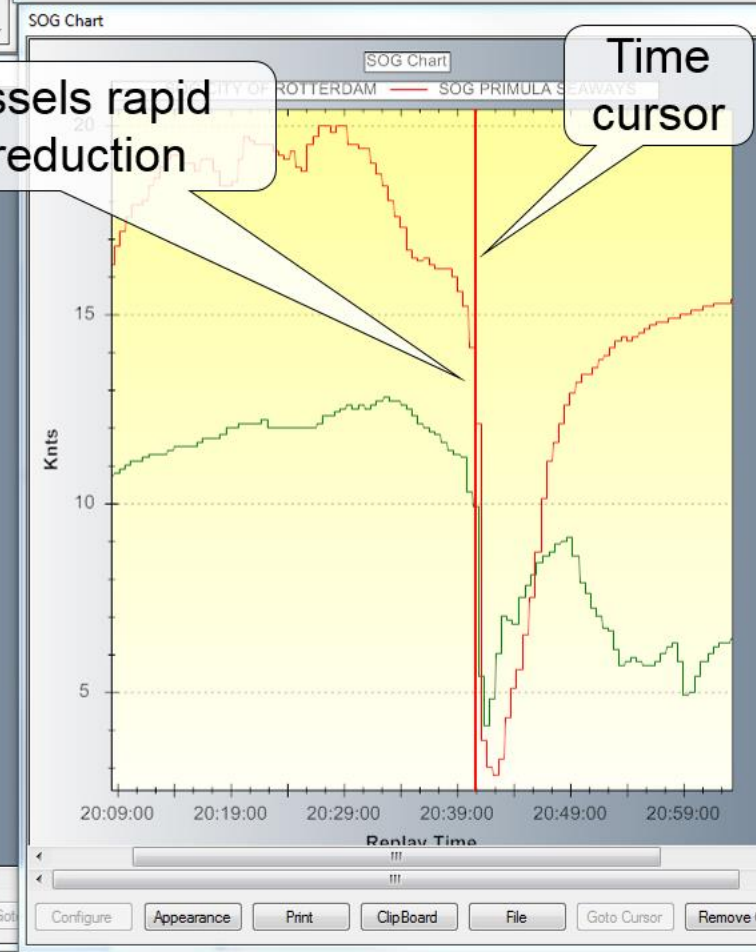
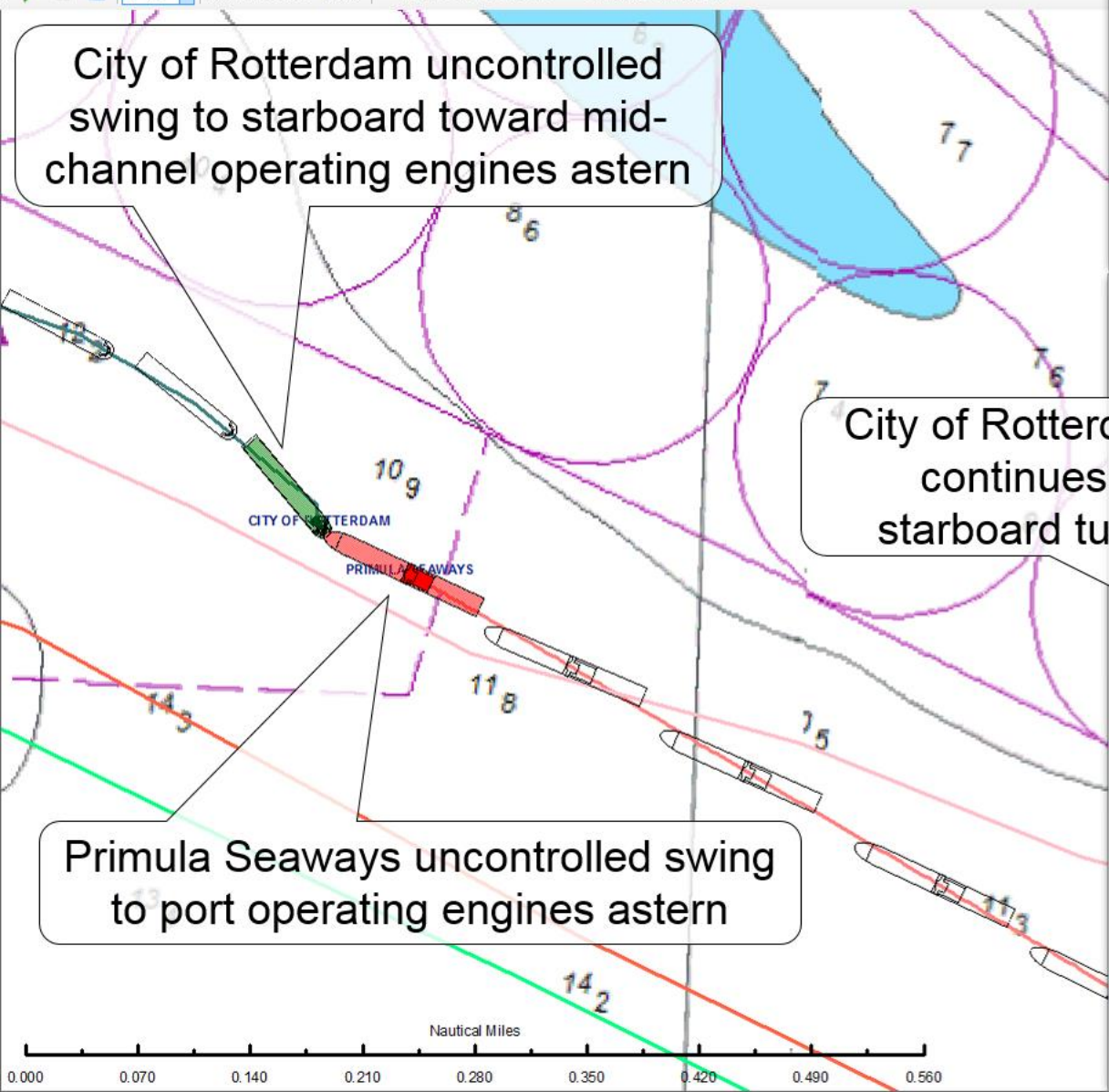
| PRIMULA SEAWAYS | | | |
|-----------------|------------|-----------|----------|
| Date | 03/12/2015 | Time | 20:40:32 |
| Latitude | 53.58491 | Longitude | 0.04511 |
| Heading | 295.00 | COG | 297.40 |
| SOG | 14.10 | | |

Replay Time Settings

Data Start and End Times
 Start: 03/12/2015 20:00:00 End: 03/12/2015 21:15:55

Replay Start and End Times
 Start: 03/12/2015 20:00:00 End: 03/12/2015 20:40:00

Current Replay Time
 03/12/2015 20:40:00

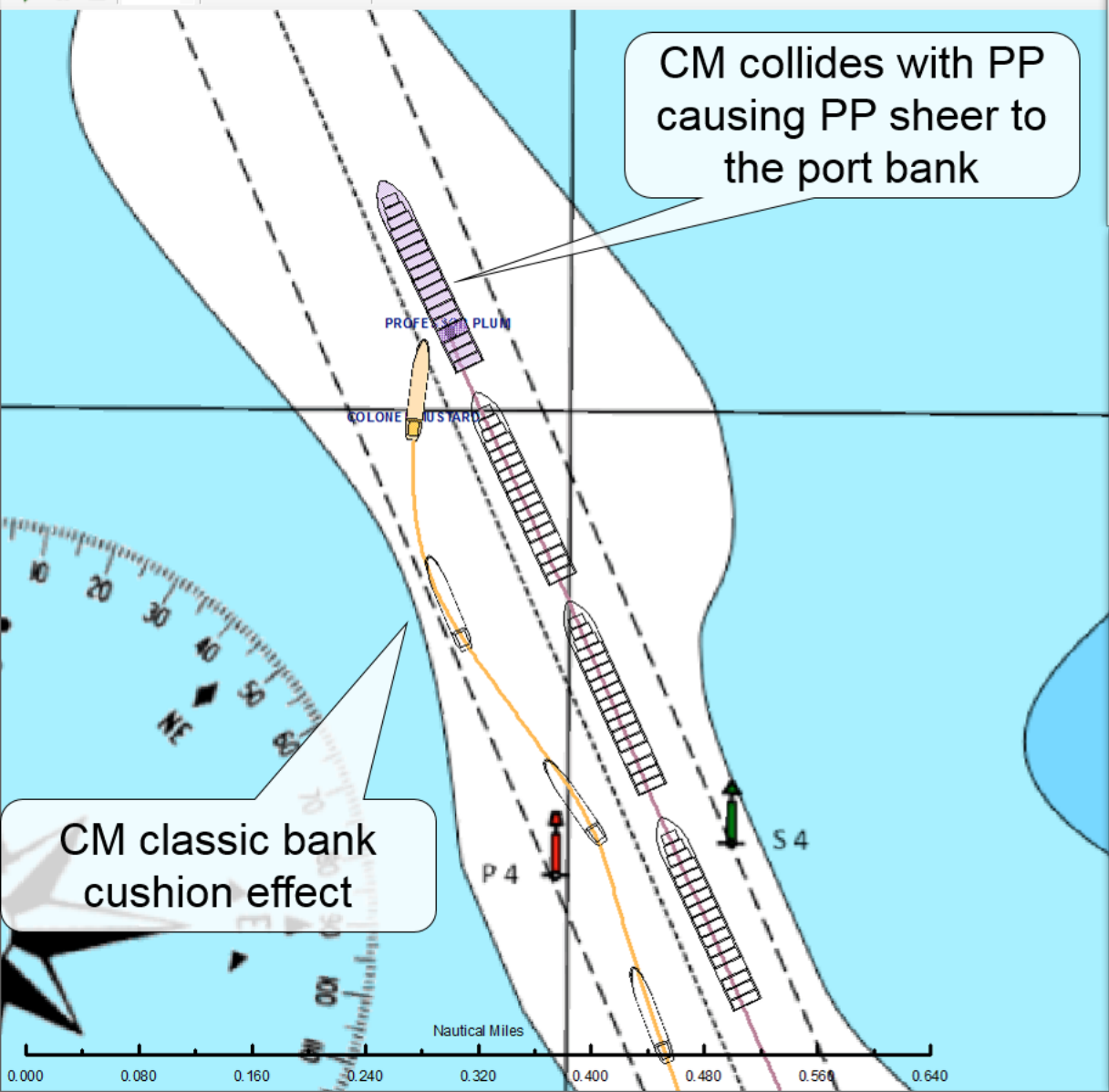




Case 3: COLONEL MUSTARD c/w PROFESSOR PLUM

- April Fool's Day 2016, Canal Interaction
- Full VDR both vessels
- Daylight good visibility and benign conditions
- PROFESSOR PLUM 5x the displacement of COLONEL MUSTARD
- PROFESSOR PLUM allowed overtake of COLONEL MUSTARD.





CM collides with PP causing PP sheer to the port bank

CM classic bank cushion effect

Replay Time Settings

Data Start and End Times
 Start: 01/04/2016 07:18:00 End: 01/04/2016 07:45:01

Replay Start and End Times
 Start: 01/04/2016 07:18:00 End: 01/04/2016 07:45:01

Current Replay Time
01/04/2016 07:34:06

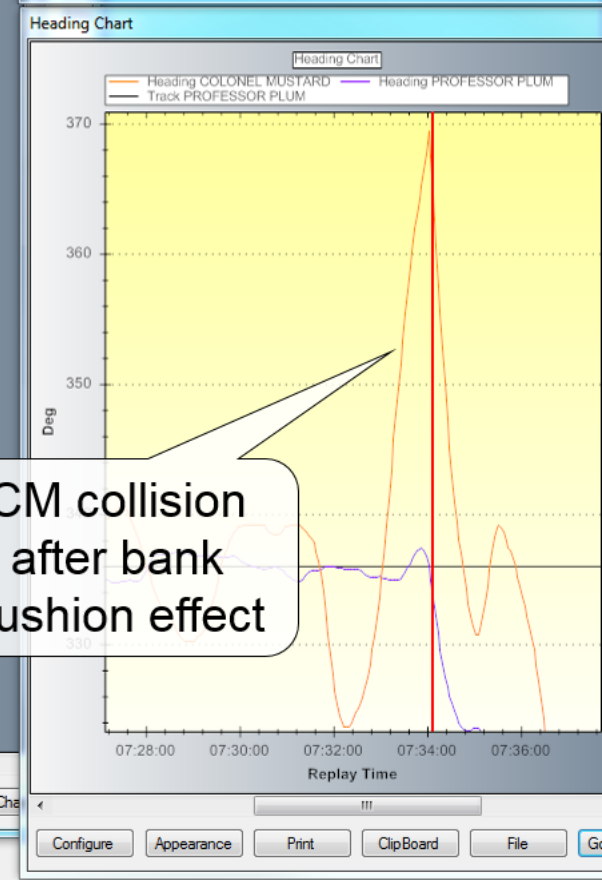
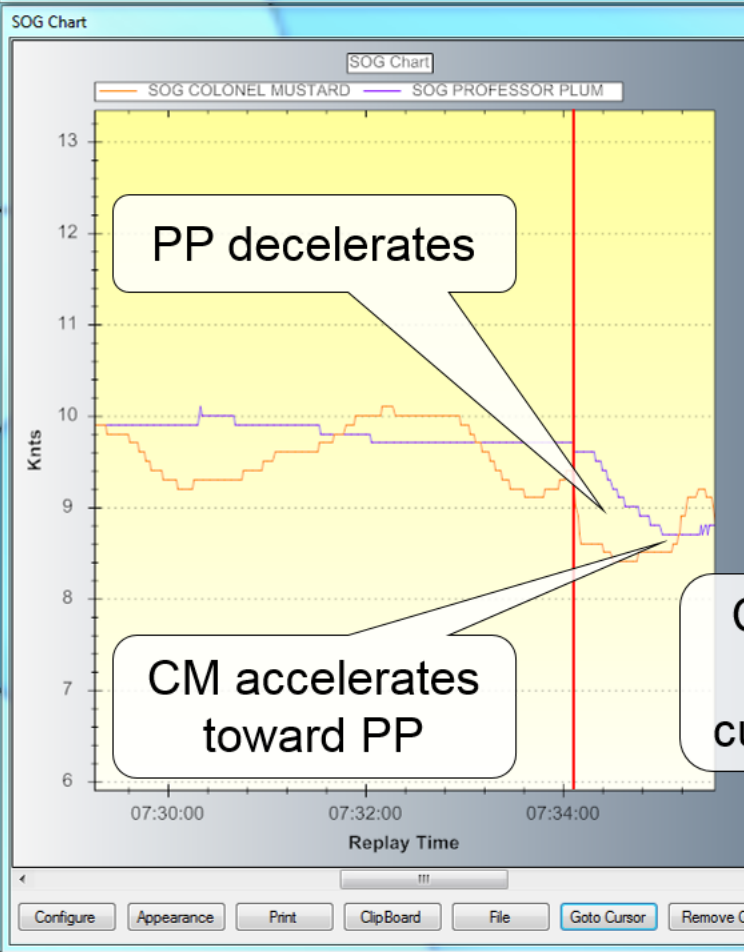
Navigation Data

COLONEL MUSTARD

| | | | |
|----------|------------|-----------|-----------|
| Date | 01/04/2016 | Time | 07:34:06 |
| Latitude | 29.43324 | Longitude | 122.16454 |
| Heading | 365.90 | COG | 360.10 |
| SOG | 9.30 | LOG | 9.30 |
| Depth | 9.1 | | |

PROFESSOR PLUM

| | | | |
|----------|------------|-----------|-----------|
| Date | 01/04/2016 | Time | 07:34:06 |
| Latitude | 29.43436 | Longitude | 122.16498 |
| Heading | 334.00 | COG | 339.90 |
| SOG | 9.70 | ROT | -25.9 |
| Depth | 3.4 | Track | 336.0 |

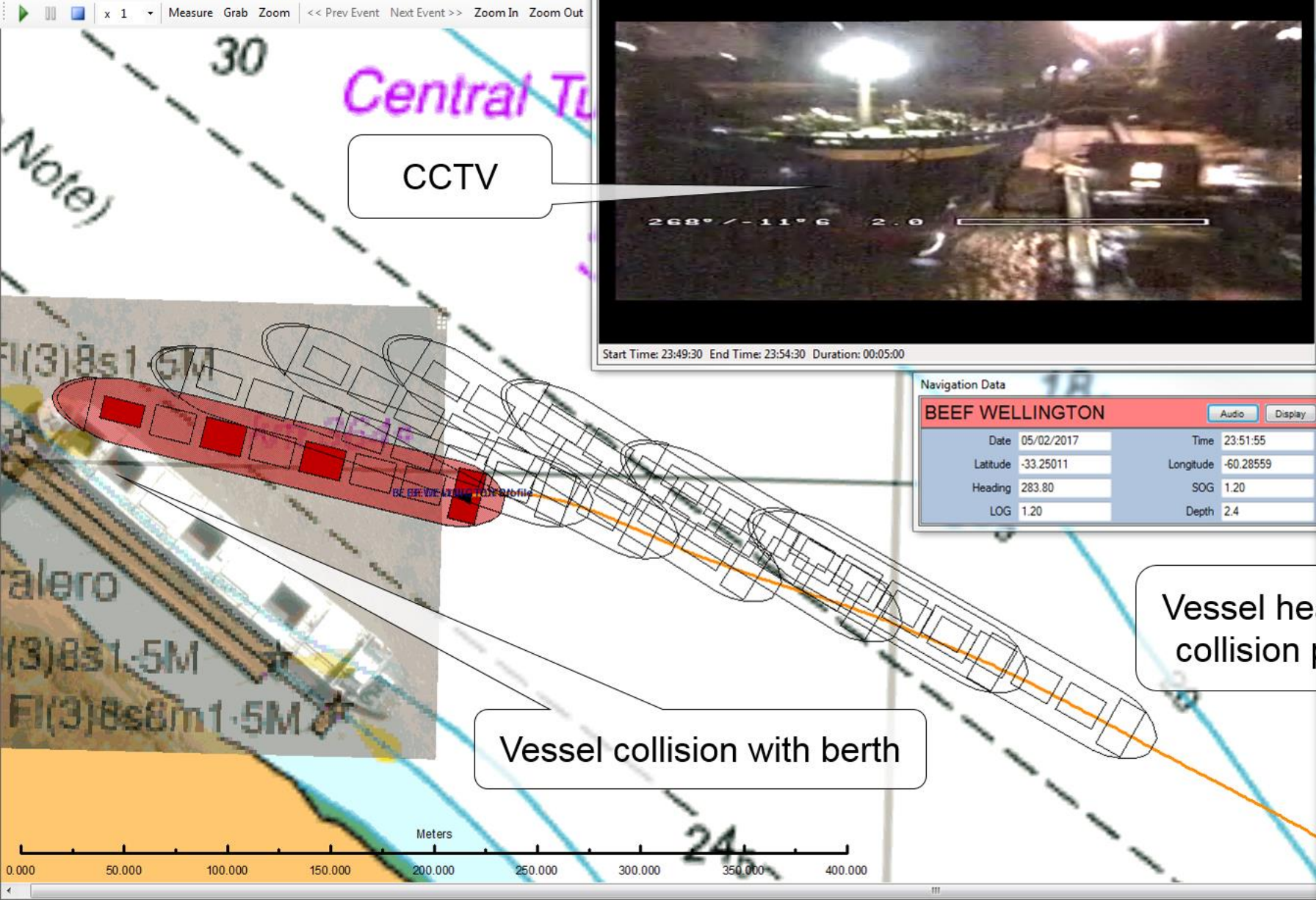




Case 4: BEEF WELLINGTON Fixed Object Damage

- 5th February 2017, South America
- Full VDR and shore-side CCTV
- Full darkness in calm conditions
- Berthing against strong river current
- No tugs in attendance.





Start Time: 23:49:30 End Time: 23:54:30 Duration: 00:05:00

Replay Time Settings

Data Start and End Times
Start: **05/02/2017 22:55:00** End: **06/02/2017 00:45:00**

Replay Start and End Times
Start: 05/02/2017 23:45:00 End: 05/02/2017 23:55:00

Current Replay Time
05/02/2017 23:51:55





Conclusions





Conclusions

- Specialist tools are needed to decipher electronic evidence
- Forensic analysis provides incontrovertible evidence
- Tools of the trade are 2-D analysis and 3-D visualisation
- The facts and causation can be quickly agreed
- Parties can quickly agree 'liability' and settle 'costs'.





Marine Accident Analysis of Collisions and Groundings:

How to learn from past incidents to avoid them in the future

Webinar: International Union of Marine Insurance

10 April 2018





ONE PARTNER. WORLDWIDE SUPPORT.

